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# Computer Modeling of Close-to-Ground Tornado Wind-Fields for Different Tornado Widths

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Computer Modeling of Close-to-Ground Tornado Wind-Fields for Different Tornado Widths

A thesis submitted in partial fulfillment of the requirements for the degree of Master of Science in Civil Engineering

by

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# August 2018 University of Arkansas

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This thesis is approved for recommendation to the Graduate Council.

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المنسارات



#### **ABSTRACT**

Tornadoes induce different wind forces on buildings than straight-line (SL) winds. The tangential velocity  $(V<sub>θ</sub>)$  of tornados is the main parameter that causes damage to the buildings. In-field tornado measurements cannot evaluate the tornado's  $V_{\theta}$  at less than 20m above ground level (AGL). The laboratory tornado simulators suggest that the Swirl ratio (S) and the radius  $(r_0)$  are the most influential factors affecting Vθ. However, due to scaling problems, laboratory simulators cannot report the  $V_\theta$  for elevations less than 10m AGL. Well refined computational fluid dynamics (CFD) models can evaluate the  $V_{\theta}$  at less than 10m AGL. However, the CFD models are limited to tornado radius ro=1.0km whereas observation of actual tornados by National Weather Service (NWS) shows that significant tornados in USA have width in the range of 0.7km to 2.3km. Thus, effect of  $r_0$  on the V $\theta$  is not investigated. Therefore, the aim of this study is to investigate the maximum  $V_\theta$  ( $V_{\theta,\text{max}}$ ) for different tornado radii at elevations above and below 10m AGL. Simulation results show that by increasing the r<sub>o</sub>, the S parameter producing the  $V_{\theta, max}$  will increase accordingly. In addition, results show that by increasing  $r_0$ , the V $\theta$ , max gradually reduces with respect to reference radial velocity V<sub>r∞</sub>. In this respect, for 0.7km≤ r<sub>o</sub> ≤2.3km the V<sub>θ,max</sub> is in the range of 6.5V<sub>r∞</sub> to 3.0V<sub>r∞</sub>. Moreover, by increasing r<sub>0</sub>, the elevation of occurrence (z<sub>max</sub>) of the  $V_{\theta, max}$  will increase; However for all tornado radii, the z<sub>max</sub> is always between 21m to 64m AGL. In addition, simulations show that for r<sub>0</sub>≤1.6km the radial V $_{\theta}$  profiles above 10m of the ground resemble the Rankine Combined Vortex Model (RCVM) flows, whereas at less than 10m of the ground the profile has two peaks for S greater than the touchdown S. Similarly, for  $r_0 \ge 1.8$ km the radial V $\theta$  profiles below and above z=10m have two peaks for the S greater than the touchdown S.



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Special thanks are extended to my advisor Dr. R. Selvam for his unconditional support, time and guidance during this work. I am thankful for the opportunity he gave me to work on the project upon to use his tornado modeling program and his training on Tecplot software. Besides my advisor, I would like to thank the rest of my thesis committee members: Dr. Heymsfield and Dr. Hale, for their insightful comments and encouragement.

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I would also like to thank to my father, mother, brother and sister who always supported and encouraged me.



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المنسأوة الاستشارات





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$$
\lim_{\omega\rightarrow\infty}\mathbf{Z}(\mathbf{K}^{\text{in}}(\mathbb{R}^d))
$$

# **NOMENCLATURE**









# *Greek symbols*





#### **CHAPTER 1. INTRODUCTION AND OBJECTIVES**

<span id="page-16-0"></span>The United States experiences a higher number of annual tornados than all other countries. An average of 1200 tornados occur within the USA each year killing up to 60 people and injuring more than 1500 people. Additionally, tornados cause \$148 million building damages to the United Sates annually, and are the second largest cause of damage after hurricane in this country (NWS, 2010). A major reason for the continued devastations by tornados is an inadequate understanding of this type of wind storm and its loading on structures.

## <span id="page-16-1"></span>**1.1. Tornado forces on buildings**

The force that tornados exert on buildings is different from straight line (SL) atmospheric boundary layer (ABL) flows. Jischke and Light (1979 & 1983), Bienkiewicz and Dudhia (1993), Selvam and Millet (2003), Mishra et al. (2005), Zhao et al. (2016) and Yousef (2017) reported the mean surface pressures due to tornado to be in the range of 2.5-5 times higher than the SL flows. Likewise, the tornado-induced lateral and vertical forces on structures are, respectively, 1.5 times and 3 times higher than those by ASCE 7-05 (Sarkar et al. 2006; Hann et al. 2008; Haan et al. 2010; Hu, 2011). Therefore, a properly designed structure for the SL boundary layer flow might fail for a tornado-wind of the same speed (Selvam and Millett, 2003), and thus the existing building codes and provisions fail in predicting tornadic wind loads.

#### <span id="page-16-2"></span>**1.2. Difference between the SL and tornadic winds and forces**

Figure 1.1 shows SL and tornadic flows. It can be seen in this figure that SL flow behavior is directly proportional to height, and translates across the isobars (Figure 1.1.a). On the other hand, a tornado is a narrow, violently rotating column of air that produces vortices with significant tangential velocity components (Figure 1.1.b). In a SL wind, wind flows in one direction as shown



in Figure 1.1.a; whereas a tornadic flow has three velocity components: radial velocity  $(V_r)$ , tangential velocity (V $_{\theta}$ ), and vertical velocity (V<sub>z</sub>). Out of these three components, V $_{\theta}$  is more intense than  $V_r$  and  $V_z$  (Church, 1979; Ishihara and Liu, 2014, Vatistas, 1998). Therefore, in order to design the buildings for tornados, the maximum  $V_{\theta}$  (V $_{\theta,\text{max}}$ ) of the tornados should be investigated.



Figure 1.1. Main velocity components for: a) SL boundary layer wind; b) tornado wind

## <span id="page-17-0"></span>**1.3. Importance of Vθ,max and computer modeling of tornados**

The  $V_{\theta}$  profile in the field can be obtained from Doppler radar measurements. Refan et al. (2017) analyzed five different tornado data and reported their  $V_{\theta, max}$ . One of the drawbacks of the Model of Refan et al. (2017) is that they can only provide the V $_{\theta}$  profile above 30m above ground level (AGL) due to the blocked reflection close to ground (Doswell et al. 2009; Wurman and Kosiba, 2013). On the other hand, wind engineers are interested in wind profiles close the ground for the following reasons: first, most buildings are within 10m from the ground; second, several studies show that the  $V_{\theta, max}$  occurs close to the ground.

In order to understand further details of the  $V_{\theta}$ , laboratory tornado vortex chambers (TVCs) are used (Ward, 1972). The V $_{\theta}$  in the laboratory TVCs is influenced by the following parameters (Maxworthy,1972; Davies-Jones, 1973): Reynolds number (Re), the aspect ratio (AR), and swirl ratio (S), as given below:



$$
R_e = \frac{(V_{r\infty})(\text{Inlet height})}{v}
$$
 Eq. (1.1)

Where  $V_{r\infty}$  is the radial velocity of the tornado and v is the kinematic viscosity of air. Using  $Re \geq 4.5x104$  in the TVC models make the tornado simulations independent of the R<sub>e</sub> as reported by Refan and Hangan (2017).

$$
AR = \frac{H_o}{r_o}; \tEq. (1.2)
$$

where  $r_0 = 0.5$ \*width of the tornado, and is the radius of TVC, and  $H_0$  is the inflow height. Also,

$$
S = \frac{V_{\theta}}{2(AR)V_{\text{r}}} = \frac{V_{\theta}}{2(\frac{H_0}{r_o})V_{\text{r}\infty}};
$$
 Eq. (1.3)

Eq (1.3) implies that S and  $r_0$  influence  $V_\theta$ . Figure 1.2 shows these TVC parameters.

However, the relatively small size of the laboratory simulators results in large geometric scaling ratios (Refan and Hangan, 2017), thus they cannot evaluate the close-to-ground  $V_{\theta}$ . In this regard, Refan (2014) proposed a simulator with scale of 1:11, but this model cannot measure  $V_{\theta}$  at less than 35m AGL. Therefore, the laboratory simulators are incapable of measuring the close-toground  $V_{\theta}$ . To solve this problem, computer models can be used. For particular  $r_{o}$  or S parameters, extensive studies using computational fluid dynamics (CFD) simulation models are conducted. CFD models of Rotunno (1977), Lewellen et al. (1997, 1999), Kuai et al. (2008) and Gallus et al. (2006) are limited to the minimum elevation of 20m AGL. The CFD model of Dominguez and Selvam (2017) was able to evaluate the V $\theta$  at less than 10m AGL, but the radius was limited to  $r<sub>o</sub>=1.0$ km in their study. However, observations of actual tornados by National Weather Service (NWS) shows that significant tornados in USA have radii in the range of 0.7km to 3.2km. Therefore, in the CFD models, the effect of  $r_0$  on the V $\theta$ , max is not investigated so far and the computer modeling should be further investigated for different tornado  $r_0$  radii.





Figure 1.2. Schematic of a TVC and its parameters

# <span id="page-19-0"></span>**1.4. Aim and objectives of the study**

Dominguez and Selvam (2017) proposed a CFD model to simulate a tornado chamber of 1.0kmx2.0km. They used minimum grid spacing (MGS) of 0.001H<sup>o</sup> in the vertical axis, where Ho=1000m; rendering that their model captured the spacing of 1.0m close to the ground. However, their model is limited to the tornado radius of  $r_0$ =1.0km, and the V $\theta$  profile for other tornado radii are not investigated. Therefore, the present study will propose a CFD model to determine the  $V_{\theta, max}$ for various r<sup>o</sup> radii above and below 10m AGL. Based on these, the objectives of the study are formulated as follows:

# **Objective 1:** To investigate the effect of the tornado radii on the  $V_{\theta, max}$

Lewellen et al. (1999) postulated that by changing  $r_0$  parameter the V $_{\theta, max}$  will change. Dominguez and Selvam (2017) used a CFD model and reported that for  $r_0=1$ km the V $\theta_{\rm max}$  is approximately 5.0V<sub>r∞</sub> which occurs at elevation ( $z_{max}$ ) of 28m AGL with S=0.6; however other tornado radii were not investigated in their study. Hangan and Kim (2008) stated that by changing the r<sup>o</sup> the S



parameter producing the  $V_{\theta, max}$  will change, but they did not report the S value for different  $r_0$  radii. Therefore, as the first objective of this study, the S parameter producing  $V_{\theta, max}$  are determined for  $0.7 \text{km} \leq r \leq 2.3 \text{km}$ , which is the range of common tornados in the USA as reported by NWS. In addition, the r<sub>c</sub> and  $z_{\text{max}}$  for 0.7km $\leq$ r<sub>o</sub> $\leq$ 2.3km are investigated.

#### **Objective 2: To investigate the Vθ,max below 10m AGL for different r<sup>o</sup> radii**

Although the  $V_{\theta}$  close to the ground is the major cause of building damages, the laboratory and CFD models cannot report the V $\theta$  at less than 10m AGL (Dominguez and Selvam, 2017), whereas typical buildings are located at  $z=3.3m$  AGL. Dominguez and Selvam (2017) reported the V $\theta_{\text{max}}$  a z=3.3m AGL for r<sub>o</sub>=1.0km. Thus, the present study will investigate the V $_{\theta, max}$  for 0.7km $\leq$ r<sub>o</sub> $\leq$ 2.3km at  $z=3.3m$  AGL.

#### **Objective 3: To investigate the effect of r<sup>o</sup> on the V<sup>θ</sup> profile close to the ground**

Previous studies show that the  $V_{\theta}$  profile of tornados at different elevations resemble the Rankine Combined Vortex Model (RCVM) flow. However, Dominguez and Selvam (2017) showed that for r<sub>o</sub>=1.0km the radial V $_{\theta}$  profile at z<10m has two peaks and no longer resembles the RCVM profile. Church et al. (1979) asserted that occurrence of two peaks on the radial V $\theta$  profile close to the ground is due to a strong shear force and is the main cause of destructive effect of tornados on buildings. Therefore, as the third objective of this study, the radial  $V_{\theta}$  profiles of different tornados with  $0.7 \text{km} \leq r_0 \leq 2.3 \text{km}$  at different elevations are investigated.



#### **CHAPTER 2. LITERATURE REVIEW**

<span id="page-21-0"></span>The main goal of this literature review is to conduct a comprehensive analysis of the current state of knowledge on the tornado flows. The literature review begins with a brief review of the basic information about tornados. Afterward, the techniques of measuring the tornados' velocity and intensity are discussed. Then, the in-field and the post-damage investigation techniques are reviewed. Subsequently, techniques of modeling the tornados, including the analytical, laboratory and CFD models are also presented and their pros and cons are discussed.

# <span id="page-21-1"></span>**2.1. Tornado as an atmospheric phenomenon**

A tornado is a high-speed short-term rotating storm. This phenomenon can have a maximum velocity of 300 mph, and its damage paths can be in excess of 4.5km and 80km long. Tornados rotate counter-clockwise in the Northern Hemisphere and clockwise in the Southern Hemisphere. This phenomenon is visible as a vortex which rotates about a hollow cavity as a whirlpool structure of winds which produce centrifugal forces. As condensation occurs around the vortex, a pale cloud appears and tornado funnel becomes visible. Funnels usually appear as an extension of the dark, heavy cumulonimbus clouds of thunderstorms, and stretch downward toward the ground (Huschke, 1959). However, some of these funnels never touch the ground, and some of them touch and rise again. Genesis of the tornado and its structure are discussed in the following sections.

# <span id="page-21-2"></span>**2.2. Tornado genesis and formation**

Allaby (1997) stated that tornadoes are produced by the combined effects of thermal and mechanical forces, with one or the other force being the stronger generating agent. NOAA (2010) stated the reason of the tornado genesis in the USA is interaction of the warm moist Gulf air with the cold and dry Canadian air coming via the Rockies.



Figure 2.1 shows the process of genesis of the tornado as presented by NOAA (2010). It can be seen that before the process of tornado genesis has three stages. In the first stage, thunderstorms develop, a change in the wind direction and an increase in the wind speed with the height happens which causes an invisible horizontal spinning effect in the lower atmosphere. In the second stage, the rising air within the thunderstorm updraft tilts the rotating air from horizontal to vertical. In the third stage, an area of rotation extends through the storm body. Most tornados form within this area of strong rotation.



Figure 2.1. Tornado genesis and formation (NWA, 2010). a) Stage one; b) Stage 2; c) Stage 3

# <span id="page-22-0"></span>**2.3. Tornado structure**

Structure of tornados can be studied from two perspectives: the general structure which shows its different regions, and the vertical structure, which shows the number of its cells.

# <span id="page-22-1"></span>**2.3.1. General structure of tornados**

Figure 2.2a depicts the main features of the tornado as defined by Whipple (1982). As can be seen in Figure 2.2, a rotating funnel cloud is in contact with both the ground and the wall cloud. The rate of the circulation is decreasing away from the tornado vortex core, and a characteristic air suction is observed inside the vortex.



Wurman et al. (1996) provided more precise representation of the structure of the tornado, as shown in Figure 2.2b. They analyzed the data obtained from the Doppler Radar for a real tornado and distinguished five different flow regions, as shown in Figure 2.2b. In their model, Region I is the outer-flow region, which is above the boundary layer region and extends at least 1km above the vortex core. Region II represents the core of the tornado. This region is associated with high wind velocities and a pressure drop. Region III can be described as a tip of Region II. There, the tornado flow is intensified and disturbed by frictional interaction with the surface. Around Region III, there is the surface boundary layer region (Region IV), and in Region V the angular momentum of the vortex is concentrated and transported downward.



Figure 2.2. a) Structure of tornado vortex. a. Model of Whipple (1982); b) Tornado vortex with distinguished various flow regions (Wurman, Straka and Rasmussen, 1996).

# <span id="page-23-0"></span>**2.3.2. Vertical structure of tornados**

Lewellen (1976) and Davies-Jones (1986) stated that with increasing the S parameter of the tornado models, the tornado vortex evolves from a jet-like flow to a one-cell vortex which is characterized by an axial up-flow in the centerline (Figure 2.3.a). Afterwards, stagnation point and



vortex breakdown occur aloft (Figure 2.3.b)., and double-cell tornado occurs, which is characterized by apparent downdraft in the center of the tornado (Figure 2.3.c). Occurrence of double-cell tornado is the stage at which the  $V_{\theta, max}$  occurs. Refan (2014) and Refan et al. (2014) also suggested the same structures for the single- and double-celled tornados.



Figure 2.3. a) Vertical structure of single-cell; b) Vortex breakdown aloft; c) Vertical structure of the double-cell (Davies-Jones, 1986)

# <span id="page-24-0"></span>**2.4. Size, speed and duration of tornados**

As an NWS report in 2012 defines, the tornados can be categorized as weak, strong and violent tornados as shown in Table 2.1. However, their classification does not provide information on the tornado damages to the buildings, Therefore, researchers turned their attention to connecting the tornado speed to the damages they cause to the buildings.

Tornado severity	Weak tornado	Strong tornado	Violent tornado
Frequency $(\% )$	88	11	
Death ratio(%)	Less than 5	Almost 30	70
Lifetime (minute)	$1 - 10$	>20	>60
Speed (mph)	$<$ 110	10-205	>205

Table 2.1. Tornado severity report (NWS, 2012)



# <span id="page-25-0"></span>**2.5. Tornado intensity classification**

Intensity of the tornados and the damage they cause to the buildings is classified by methods Fujita and Enhance Fujita (EF) scales. These scales are explained by detail in this section.

## <span id="page-25-1"></span>**2.5.1. Fujita intensity scale**

The most important parameter to classify the tornado intensification and its damage to the buildings is its wind speed (Fujita, 1971). Thus, Fujita (1971) proposed a statistical method to scale a tornado intensity using the tornado velocity. He related the maximum tornado wind velocity to the intensity based on the observed damage investigations. However, the velocities in Fujita Scale are greatly overestimated (Grazulis, 1993). Therefore, attempts were made to modify the Fujita scale (McDonald, Forbes and Marshall, 2004).

# <span id="page-25-2"></span>**2.5.2. Enhanced Fujita (EF) intensity Scale**

In 2004, the Fujita intensity scale was modified in Texas Tech University (McDonald, Forbes and Marshall, 2004), and was named as EF scale. The EF scale provides a better correlation between the tornado damage and its maximum wind speed (NOAA, 2012). A comparison of the F and EF intensity scales is shown in Table 2.2.

Fujita Scale (F)	3-sceond gust speed (km/h)	Enhance Fujita Scale(EF)	3-sceond gust speed (km/h)
F <sub>0</sub>	73-127	EF <sub>0</sub>	105-138
F <sub>1</sub>	128-190	EF1	139-177
F <sub>2</sub>	191-261	EF <sub>2</sub>	178-222
F <sub>3</sub>	262-339	EF <sub>3</sub>	223-271
F4	340-424	EF4	272-323
F5	425-514	EF <sub>5</sub>	324-380

Table 2.5. Comparison of Fujita (F) and Enhance Fujita (EF) intensity scales



# <span id="page-26-0"></span>**2.6. Frequency occurrence and the death rate of tornados**

NOAA (2012) classified the death-related statistics of the tornados of 1950 to 2012 based on Fscale. They related the percentage of the number of the deaths due to each Fujita scale tornado is shown in Figure 2.4. NOAA (2012) reported that among 1704 tornados in 2011, only 5% of them fall in the category of EF3 to EF5, whereas 95% of tornados fall in the categories of EF0 to EF2. This figure implies the importance of providing a better design for the highly intense tornados, and for this purpose, the tornado wind profile should be investigated first. Hence, the next section reviews studies of the wind velocity profile.



Figure 2.4. Percentage of the tornado-related deaths by Fujita scale from 1950 to 2011

# <span id="page-26-1"></span>**2.7. Investigation of the wind velocity profiles**

Studies pertaining to the wind velocity of tornados can be categorized as in-field measurements, and post-damage investigations. Each of these techniques has its own subclasses which are discussed in the following sections.



#### <span id="page-27-0"></span>**2.7.1. In-field measurements**

#### <span id="page-27-1"></span>**2.7.1.1. Doppler radar measurements**

The spatial distributions of Doppler velocities can be used to study special characteristics of tornadoes (Doviak and Zrnic,1993; Wuman et al. 1997). The mechanism of Doppler radar to measure the tornado parameters is straightforward. The radar initially quantifies only the wind toward and away from the radar. Afterwards, the radar measurements will be connected to Doppler spectra of tornadoes by showing a model of tornado circulation. Since using Doppler radars facilitates data collection of the tornado-induced damages (Wuman et al. 1997), different configurations of the Doppler radars have been used to collect the data of over 200 individual tornados (Wurman, 1997; Lee and Wurman, 2005; Wurman, 2002; Kosiba, Trappa and Wurman, 2008; Wakimoto et al., 2012; Wurman et al., 2013).

Using Doppler Radar for tornados revealed that the  $V_{\theta}$  profile is similar to the Rankine model profile. The Rankine profile is often called Rankine Combined Vortex Model (RCVM) (Kilty, 2005). In the RCVM, the flow has two separate flow fields. In the interior flow field (inner core), the  $V_{\theta}$  increases linearly with the radius, and peaks at a point which is called core radius (rc). In the outer flow (tail), the  $V_\theta$  declines inversely with radius from the r<sub>c</sub> outward. The RCVM profile of Mulhall tornado is shown in Figure 2.5.





Figure 2.5. Rankine Model profile of an actual tornado (Taken form Lee and Wurman, 2005)

Likewise, Wurman and Alexander (2005) and Kosiba, Trappa and Wurman (2008) compared the observed tornado damage with retrieved Doppler Radar data, interpolated velocity fields and compared them with F-scale estimates. Their comparison revealed that radar-based estimates of the F-scale intensity usually exceeded the damage-survey-based F-scale. Table 2.3 presents a summary of some of the tornados that were investigated by Doppler Radar technique. Table 2.3 shows the Doppler radar measurements determine the  $V_{\theta, max}$  at elevations above 50m.

Although the Doppler radar technique offered valuable insight of the tornado velocity profile and tornado structure, its measurements have some drawbacks. The most important drawback is that the Doppler Rada measurements is that they cannot evaluate the close-to-ground wind field, rather they are limited to about 50m from the ground (Wurman et al. 2007). This limit is due to the beam restrictions of the Doppler radars. In order to solve this problem, Wurman et al. (2003) used Doppler on Wheels for the Spencer tornado of 1998. However, they could not capture less than 30m AGL. Also, Wurman et al. (2013) used mobile Doppler radars and reported that the  $V_{\theta, max}$ remains constant at less than 30m, which is in contrast to the reality (Lewellen et al., 2008; Wakimoto et al., 2012). Furthermore, the Doppler radar investigation is always associated with the



injuries of the crew, and is thus unsafe (Wurman et al., 2014). Lastly, Doppler radar measurements suffer from the physical obstacles that exist in the field (Dominguez and Selvam, 2017).

$= 0.004$						
Tornado	Maximum $V_{r\infty}$ (m/s)	$V_{\theta, max}(m/s)$	$r_c(m)$	$z_{\rm max}(m)$		
Mullhal, OK (1999)	<b>NA</b>	100	700	50		
El Reno, OK (2013)	20	60	650	175		
Bridge-Creek-Moore, OK (1999)	<b>NA</b>	126	175	50		
Spencer, SD (1998)	30	101	700	50		
Hong Kong $(2004)$	<b>NA</b>	22	30	$\sim 50$		

Table 2.3. Doppler Radar measurements of some actual tornados

#### <span id="page-29-0"></span>**2.7.1.2. Ground-Based Velocity Track Display (GBVTD)**

In order to rectify the drawbacks of the Doppler radar measurements, the mathematical technique of Ground-Based Velocity Track Display (GBVTD) is employed by some researchers. The GBVTD uses the data of the Doppler radar measurements to measure the  $V_{r\infty}$  and  $V_{\theta}$  close to the ground. The GBVTD analysis consists of four steps: filtering the raw radar data, transforming the data into a Cartesian grid, identifying the center of the vortex and retrieving tangential and radial velocity components through the algorithm. Refan et al. (2017) used this technique to determine the tornado features of five actual tornados: Spencer, SD 1998 (F4), Stockton, KS 2005 (F1), Clairemont, TX 2005 (F0), Happy, TX 2007 (EF0) and Goshen County, WY 2009 (EF2) Likewise, Kosiba and Wurman (2013, a, b) used this technique to determine the tornadic features of Russel, Ks 2014 and Happy TX tornados. A summary of the findings of the GBVTD is given in Table 2.4. However, Nolan (2013) claimed that the velocities obtained by the GBVTD are biased. Nolan (2013) showed that the close to ground  $V_{\theta}$  profile of the GBVTDs is affected by the effect of the debris. This problem is more accentuated for smaller or weaker tornados.



Tornado	Maximum $V_{r\infty}$ (m/s)	$V_{\theta, max}$ (m/s)	$r_c(m)$	$z_{\text{max}}(m)$	Reference
Spencer, SD (2003)	30	80	105	20	Hangan and Kim, (2008)
Mulhall, OK (1999)	NA	80	NA	50	Lee and Wurman, (2005)
Manchester, SD (2003)	~20	80	130	20	Gallus and Sarkar (2010)
Goshen, Wyoming (2009)	10	41	140	30	Wurman et al (2013)
Dimmit, Texas (1995)	50	60	150	Na	Wurman and Gill (2000)
Tuscaloosa, AL (2011)	76	43	Na	NA	Karstens and Gallus (2013)
El Reno, OK (2013)	20	Na	650	50	Bluestein et al., 2016
Moore, OK (2013)	50	80	NA	NA	Ortega et al. (2014)
Russel, Ks (2012)	NA	43	80	5.0	Kosiba and Wurman (2013)
Happy, TX (2002)	NA	36	160	NA	Refan et al. (2017)

Table 2.4. GBVTD analysis of some actual tornados

# <span id="page-30-0"></span>**2.7.2. Post-damage investigations**

# <span id="page-30-1"></span>**2.7.2.1. In-field post-damage investigation**

Mehta et al. (1976) investigated the damage of the 1974, Canada tornado using in-field data collection by locating 148 damage survey spots and concluded that the appearance of the damage cannot be related to the wind speeds. They suggested that adoption of wind load criteria that focus on details of design materials can help reduce the damage to the buildings. Chmielewski et al. (2008) investigated the damage of a tornado occurred near Opole, Poland in 2008. In their study, they investigated the damages on the structures and found the velocity of the tornado. Likewise, Lewellen et al. (2008) assessed the effect of debris on tornados and concluded that the debris may affect tornadic flow near the surface. They also conclude that, as the damage track is the primary visual signature of tornadoes, realistic simulation of their path and width contributes to correlating



the tornado structure to the measured velocities. Selvam et al. (2015) investigated the Mayflower Tornado of 2014 through in-field investigations. In their investigation, they considered the topography effect of the area interacting with the tornado.

However, the shortcoming of the in-field post-damage investigation is that they cannot provide any detail on the  $V_\theta$  profiles, rather they only correlate the damages to the intensity scales.

# <span id="page-31-0"></span>**2.7.2.2. Photography and video observations**

Walter and Hoecker (1960) investigated the wind speed patterns of the 1957 Dallas Tornado. In their investigation, they used the movies taken by telephoto lenses from the tornado, and determined the path and wind speeds of the tornado. They reported the  $r_c$  equal to almost 60m,  $z_{\text{max}}$ equal to 90m, and the  $V_{\theta}$  approximately 78m/s, respectively. However, this method was of limited applicability, because the movie-recording facilities were not available everywhere. Moller et al. (1974, 1979) investigated a tornado in Oklahoma by using the in-field photography after the occurrence of the tornado. Using the photography technique, they could provide an estimation of the tornado velocity.

However, several drawbacks are associated with this technique. The first shortcoming is that little could be understood from the in-field photography due to poor quality of the images. In addition, because of extreme limitations in the field, measurements of the tornado velocity were nearly impossible. So, it can be concluded that photography and video observations are an outdated technique for evaluating the velocity profile.

#### <span id="page-31-1"></span>**2.7.2.3. Satellite-based measurements**

In this technique, the satellite images are used by surveyors in remote areas, from the ground, to either collect data of the tornado or correct the tornado track and differences given by other



surveyors. The significance of the satellite based measurements is pronounced in large tornados and tornado outbreaks, where the in-field measurements such as Doppler radar are inefficient and cost-intensive.

The mechanism of the satellite imagery is that the satellite sensors measure reflected solar radiation in different spectral channels across the visible and infrared energy spectrum, and then recombine the spectral channels into an image and a natural color scene. In this way, these images can be used to detect variations in surface features associated with different land cover. The physical principle guiding the use of satellite data to detect tornado damage is based on the premise that the strong winds associated with a tornado will change the physical characteristics of the surface in such a way as to alter the visible and infrared energy reflected from the surface as measured by the satellite sensor. These characteristics could be a change in the orientation of surface features or a physical change in surface reflective properties or both.

Early applications of satellite imagery were to characterize or identify severe storm damages (Klimowski et al., 1998). Yuan et al. (2002) used Indian Remote Sensing (IRS) satellite data to examine the ground track of the 1999 Oklahoma City tornado, and found out that they can track F3 and greater regions on the Fujita scale (Fujita 1981, 1987). Strong and Zubrick (2004) used the data of the National Aeronautics and Space Administration (NASA) and the U.S. Geological Survey (USGS) on the La Plata, Maryland, tornado to relate the tornado velocity to the damage. NASA and USGS used very high spatial resolution research instruments to qualitatively map the damage track of the tornado.

Jedlovec et al. (2006) explored the possibility of using the image database of NASA Earth Observing System satellites to estimate tornado damage track length and width in order to study the tornado-related damages. They used Moderate Resolution Imaging Spectroradiometer



(MODIS) and Advanced Space-borne Thermal Emission and Reflection Radiometer (ASTER) data to study the damage tracks of three tornados. It was found that, depending on the nature of the land cover, tornado damage tracks from intense tornados (F1 or greater) may be evident in the satellites. However, in the forest-covered area the scar patterns are visible while in the grassland regions, scar patterns cannot be seen at all in these satellite imageries.

Molthan et al. (2011) investigated the damage track of Alabama tornado outbreak using NASA satellite imageries. Lengths and widths of satellite-based tornado tracks were compared against official survey measurements, and it was observed that the widths obtained using NASA images are considerably less than that of the NWS. In addition, Molthan et al. (2014) concluded that it is likely the satellite-based estimates of maximum width failed to detect damage in the EF0 to EF2 range that occurred along the periphery of the surveyed tracks.

Selvam and Ahmed (2013) used the Google Earth aerial imagery data for damage investigation of terrain effects on tornado damage. Selvam et al. (2015) investigated the Mayflower Tornado of 2014 by incorporating the in-field investigations with Aerial photography from the Civil Air Patrol (CAP), NASA satellite images, and Google Earth images. Dominguez and Selvam (2016, 2017) also employed the same technique to measure the maximum width and the translating velocity of Mayflower and Tuscaloosa tornados. An example of using satellite imagery data to measure the tornado parameters in shown in Figure 2.6.

Despite their growing application, the satellite-based measurements are limited to only reporting the width and the translational velocity of the tornados, and the evaluation of the  $V_\theta$  velocity profile is impossible in this technique.





Figure 2.6. Satellite imagery measurement of a tornado using Google Map Imagery data (Dominguez and Selvam, 2017)

## <span id="page-34-0"></span>**2.7.2.4. Post-damage investigation of the National Weather Service (NWS)**

In this technique, researchers measure the tornado distance by either walking through the damage line or by using a vehicle trip (Clarke and Clarke, 2015). In large-scale tornados where these methods cannot be employed efficiently, online mapping using tools such as Damage Assessment Toolkit (DAT) are used instead. Subsequently, the data is used to calculate the path length, duration, the translational velocity and the maximum width of the tornados. Table 2.5 shows the width measurements, r<sub>o</sub> and the related intensity scales. It can be seen in this table that the tornados with intensities of EF4 and EF5 have r<sub>0</sub> in the range of 0.7km to 1.2km. The only exception is the Jarred, Texas tornado of 1997 which has r<sub>o</sub><0.1km; however, this small r<sub>o</sub> might be underestimated due to poor accessibility of the measurement techniques. Similarly, tornados with EF1 through EF3 intensity scales have  $r_0 < 0.8$ km, except for El Reno tornado with  $r_0 = 2.3$ km. It implies that the most intensive tornados of the USA are within the range of  $0.7 \le r_0 \le 2.3$ km. An example of the tornado survey by the NWS is shown in Figure 2.7.

However, the NWS technique primarily focuses on determination of the width, the path length, and the translational velocity, and does not report the  $V_{\theta}$ . Moreover, since NOAA's technique is based on in-field survey and measurement of the damage width, it considers the debris-induced



damages (Dominguez and Selvam, 2017). Meanwhile, the ground surveys are time consuming and often fail to identify the entire tornado track or damage region in sparsely populated areas because of limited vehicle access and resources (Jedlovec et al., 2006). Therefore, the width measurements of the NWS reports can only be used to estimate the relationship between of the width and the EF scale.

Tornado	Maximum width (Km)	$r_{o}$ (km)	Intensity scale	Tornado	Maximum width (Km)	$r_{o}$ (km)	Intensity scale
Joplin, Mo (2011)	1.6	0.8	EF <sub>5</sub>	<b>Tuscaloosa</b> (2011)	2.4	1.2	EF4
Moore, OK (2013)	2.1	1.05	EF <sub>5</sub>	Wheatland Wisconsin (2008)	0.18	< 1.0	EF3
<b>Bridge Creek Moore</b> (1999)	1.6	0.8	F <sub>5</sub>	El Reno (2013)	4.6	2.3	EF3
Jarrel, Texas (1997)	0.16	< 0.1	EF5	Springfield, MA (2005)	0.8		EF3
Phil Campbel (part of an outbreak) (2011)	$\overline{2}$	1	EF <sub>5</sub>	Goshen. Wyoming (2009)	$\overline{2}$	1	EF <sub>2</sub>
Cullman (part of an outbreak) (2011)	1.4	0.70	EF4	Mayflower (2014)	0.5		EF <sub>2</sub>
Flat Rock, GA (Part of an outbreak) (2011)	1.6	0.8	EF4	Parrish-Cordova (Part of an outbreak, 2011)	0.34	0.17	EF <sub>2</sub>
Spencer (1998)	1.6	0.8	F <sub>4</sub>	Pinhook (Part of an outbreak) (2011)	0.32	0.16	EF <sub>2</sub>
Manchester (2003)	1.6	0.8	EF4	Wateroak (Part of an outbreak) (2011)	0.27	0.13	EF1
Dimmit, Texas (1995)	2.0	1.0	EF4				

Table 2.5. Width measurements by NWS




Figure 2.7. Measurement of the width of the Tuscaloosa Tornado by NWS, a) maximum width of tornado; b) The path of the tornado (Taken from Dominguez and Selvam, 2017)

## **2.7.2.5. Statistical analysis techniques**

The earlier attempts of correlating the tornado parameters to the damage were done by Fujita (1971, 1981, 1987) that finally resulted in the Fujita and EF intensity scales. McCarthy (2003) described how the National Tornado Database is correlated to some aspects of the tornado damages. Brooks (2004) established a relationship between the tornado width and the EF damaging scale. They concluded that if the width of tornados increase, they become more intense. However, some actual tornados do not match with their model. Examples of this observation, as shown in Table 2.5, are the 2013 El Reno tornado which had a width of 4.6km corresponding to an EF3 scale, whereas the tornado of May 1997 tornado of Jarrell TX, had only a 0.1km path width corresponding to EF5. The reason of this mismatch is that, while the  $V_{\theta}$  is the main damagecausing component of tornados, the model of Brooks (2004) cannot include the V $\theta$ . Therefore, using Brooks' (2004) model is of poor accuracy (Dominguez and Selvam, 2017). In addition, the McCarthy (2003) and Brooks (2004) statistical techniques employ the data of other techniques,



such as the data of NWS for their analysis (Brooks, 2004). Thus the drawbacks associated with NWS measurements can also be extended to the statistical techniques.

#### **2.8. Techniques of modeling the tornados**

Previous sections showed the post-damage and statistical investigation techniques cannot report the V<sub>θ</sub> profile of the tornados. In addition, although the Doppler radars can evaluate the V<sub>θ</sub> profile of the tornados, they cannot evaluate the  $V_{\theta}$  in elevations less than 20m AGL. Therefore, researchers focused their attention to modeling the tornados in controlled environments. The tornado modeling techniques fall within one of the following categories: laboratory models, analytical models and CFD models.

#### **2.9. Laboratory models**

Ward (1972) proposed the first tornado vortex chamber (TVC) to model the tornados in the laboratory setups. Davies-Jones (1973) and Church (1979) reported that in laboratory modeling of the tornados, there are three main parameters that must be investigated carefully. These parameters are R<sub>e</sub>, S parameter, AR. The AR is  $\frac{H_0}{r_0}$ , where H<sub>0</sub> is the inflow height and the r<sub>0</sub> is the outflow radius of the chamber. Comparing the TVC model to real tornados, the outflow radius corresponds to the radius of the tornado  $(r_0)$ , where the radius is half of the width of the tornado. AR controls the size of the vortex. S parameter is the ratio of the angular momentum to the radial momentum of the vortex and is related to the tangential velocity of the tornado by  $S = \frac{V_{\theta}}{2.4 \text{ N}}$  $\frac{v_{\theta}}{2.AR.V_{r}}$ , hence variation of the V<sub>θ</sub> can change the S parameter. In addition, since the V<sub>θ</sub> is the main velocity component which is responsible for the tornado damages, the intensity of the tornados is dependent on the S parameter (Church and Snow, 1993; Jischke and Parang, 1974; Natarajan, 2011).



#### **2.9.1. Different types of laboratory models**

#### **2.9.1.1. Ward-type TVCs**

Figure 2.8 shows a Ward-Type TVC. In these models, the inputs are  $V_{\theta}$  and  $V_{r\infty}$ , and the outlet is vertical velocity on the top of the honeycomb, which is on the top of the circular cylinder. In the Ward-type models, the H<sub>o</sub> and  $r_0$  and V $\theta$  are required as input of the model (Ward 1972; Jischke and Parang, 1974). Laboratory models of Jischke and Light (1983) and Jienkiewicz and Dudhia (1993) focused on the interaction of the tornado with structures using the Ward type simulator. The earliest Ward-type simulators suffer from small S<0.5 (Davies-Jones, 1973). Diamond and Wilkins (1984) proposed a Ward type translating with a rather large r<sub>o</sub>, which is equal to 0.457m,  $H<sub>o</sub>=0.508m$ , with S=0.1 to 0.5. However, their model also has a constant  $r<sub>o</sub>$  radius, and effect of varying r<sub>o</sub> was not discussed in their model.

## **2.9.1.2. Simulator of Purdue University**

Church et al. (1977, 1979) modified the Ward type simulator and developed their Tornado Vortex Chamber-I (TVCI) at Purdue University that used a rotating wire mesh to provide circulation. Their main parameter in their simulator was the S parameter. They found a secondary circulating flow existing within the primary vortex flow. The Purdue simulators showed that that for laminar vortices, the peak velocity is highly dependent upon the S, whereas for turbulent vortices, the S dependency is weak. In the Purdue model, S could be varied from  $0$  to  $1.0$  but  $r_0$  was constant. The second generation of TVCs was generated by Snow and Lund (1985) and Lund and Snow (1993). Their suggested models had the advantage of changing the r<sub>o</sub>, and could use Doppler velocitymeter for making nonintrusive velocity measurements. However, the S range was on the lower side of the normal range (less than 1.0).



## **2.9.1.3. TVC simulator of Kyoto University**

The TVC of Kyoto University (Monji, 1985) rectified the problem of the Ward-type simulators by producing larger r<sup>o</sup> radii. This model was later used by Matsui and Tamura (2005), but the problem of this TVC model suffers from  $S \leq 1.0$ .

## **2.9.1.4. Texas Tech University vortex (TTU) simulator**

The simulator proposed by the Texas Tech University vortex (TTU) is a modified version of Wardtype simulator. The main application of the TTUs was studying the tornado-structure interaction, but not the tornado wind-field. In this regard, Wang (2001) and Wang et al. (2001), Fouts et al. (2003) and Mishra et al. (2008) used TTU and performed tests on cubical and cylindrical models. Using a scale of 1:3500 in this simulator, the TTU models have difficulties in simulating a sustained turbulence.



Figure 2.8. Ward type simulator. The Purdue University model, the Japanese Ward-type, and TTU models are modifications of this type

## **2.9.1.5. Iowa State University (ISU) simulator**

In an effort to rectify the drawbacks of the Ward-type TVCs, Sarkar et al. (2006) and Haan et al.

(2007) developed the Iowa State University (ISU) tornado simulator. The difference of the ISU



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with the Ward type was that the ISU was a closed-circuit type with the angular momentum in the flow being introduced by turning vanes at the top of an annular duct above the open test section, whereas the Ward-type had an open circuit with angular momentum being introduced by turning vanes surrounding the test chamber. Figure 2.9 shows the schematic of the ISU simulator. In the ISU simulator, the r<sub>o</sub>=75mm and is constant in their model,  $H_0$ =30mm-100mm, and S is between 0.08 to 1.4. The scale used in this simulator is scale of 1:100.

Balaramudu (2007), Haan et al. (2008), and Haan, et al. (2010) used this model to study the tornado wind-fields. However, a problem with this simulator was that the transition from a laminar core to a turbulent core that was clearly observable in the Ward-type simulators, is not observed in the ISU simulator which could be due to the instability of the vortex. In addition, the V $\theta$  velocity component and the total flow rate could not be controlled separately in this simulator (Haan et al. 2008). Moreover, the  $r_0$  variation cannot be investigated in this model.



Figure 2.9. Schematic of the ISU simulator

## **2.9.1.6. Model WindEEE Dome (MWD) simulator**

A further development to the laboratory models was the Wind Engineering, Energy and Environment (WindEEE) model (MWD) by Refan (2014) at University of Western Ontario. The schematic of the model is shown in Figure 2.10. The main concept of this simulator is similar to



that of the Ward-type model except that the MWD uses controllable fans at the periphery of the TVC to supplement the turning vanes and enhance control of the inflow and a traversing bell mouth to provide a translating source of updraft. Thus, the MWD simulator allows for variation of inflow conditions which implies that the S parameter can be controlled independently in this simulator. Moreover, while the previous laboratory TVCs could produce intensities of as much as EF2, the MWD can produce EF0-EF3 tornados.

Refan (2014) used MWD to relate the S parameter to the tornado intensity. The MWD model has a constant r<sub>o</sub> equal to 0.2m with varying simulator height up to 0.4m. The MWD has a scale of 1:16. Their model is capable of modeling tornado with the radii of up to 1.0km. Refan and Hangan (2014) reported that the vortices simulated in MWD with 0.12<*S*≤0.57 are representatives of EF0 to low-end EF1 actual tornadoes, and the ones simulated in MWD with 0.57<S<1.29 correspond to full-scale tornadoes with mid-range EF1 to low-end EF3 intensity rating. However, in the MWD apparatus, the S parameter is restricted to 0.12<S<1.30, and r<sup>o</sup> is constant.



Figure 2.10. Schematic of the MWD simulator (Refan, 2014)



#### **2.9.1.7. VORTECH Simulator**

Tang et al. (2016 and 2017) from Texas Tech University proposed the VORTECH simulator to study the effect of changing S and parameters on the  $V_{\theta}$ . VORTECH has a constant r<sub>o</sub> radius of 4m with varying inflow height of 1m to 2m. This model is the largest among all laboratory models (Figure 2.11). Scale of this model is dependent upon the S parameter to be used, and varies in the range of 1:96 to 1:500. It can evaluate the  $V_{\theta}$  at low as 10m AGL, but in their model S $\leq$ 1.0.



Figure 2.11. Schematic of the VORTECH simulators

#### **2.9.1.8. Wall of wind (WoW) Simulator**

Wall of Wind (WoW) was first introduced in 2003 at [Florida International University](https://en.wikipedia.org/wiki/Florida_International_University) (FIU) as a large scale wind engineering testing facility. However, the main focus of this model is the hurricane simulation rather than tornado modeling structures (Aly et al., 2010).

## **2.9.1.9. Summary of the laboratory TVCs**

Table 2.6 summarizes the results of all the laboratory models. It can be seen in this table that the minimum attainable elevation of the velocity profile is 10m (Tang et al., 2016 and 2017). The reason for the limitations of the laboratory models in evaluating the close-to-ground velocity is that the laboratory data is affected by the presence of the boundaries of the apparatus, measurement tools, and the scale used in the experiment (Smith, 1986; Kopp, 2016 and 2017).



Also, Table 2.7 summarizes the tornado parameters used in the laboratory models. It can be seen in this table that in all the laboratory models, the  $r_0$  range is from 0.8km to 2.0km and S≤1.0. These limits imply that these testing facilities cannot replicate the different tornado sizes, nor tornado intensities.

	I AVIC 2.0. INCSUITS OF THE IADOLATOLY			1 VQ	
Reference	Type	$r_o(km)$	Swirl ratio	$V_{\theta,max}$	Minimum z(m)
<b>Church</b> (1979)	Ward	1.5	$\overline{0}$	$\overline{NA}$	$\overline{15}$
			0.338		
			0.765		
Mitsuta (1984)	Ward	$1.0\,$	$<1.0$	12m/s	20
Monji (1985)	Ward	0.38	2.3	41m/s	40
<b>Church</b> (1993)	PU Ward	1.5	0.28	$4.5 V_{r\infty}$	~100
<b>Matsui</b> (2008)	Ward	0.15	0.14	$2.0 V_{r\infty}$	10
Mishra et al. (2008)	<b>TTU</b>	0.19	0.19	$2.5 V_{r\infty}$	NA
Matsui and Tamura (2009)	Ward	0.15	$\overline{NA}$	$\overline{NA}$	10
Lund and Snow (1993)	Ward	1.0	0.67	$\overline{NA}$	$\overline{20}$
Tari et al. (2010)	$\mathbf{ISU}$	0.75	0.08	$0.9~\mathrm{V_{r\infty}}$	~50
			0.4	4.5 $V_{r\infty}$	
			0.68	$6 V_{r\infty}$	
Lund and Snow (1993)	Ward	1.0	0.67	NA	~20
Sarkar and Haan (2005)	<b>ISU</b>	1.8	$\overline{0.5}$	$45m/s$ to 80m/s	20
Gallus et al. (2006)	ISU	$0.8 - 1.0$	1.0	75m/s to 157m/s	20
Matsui (2008)	Ward	0.15	0.14	$2.0 V_{r\infty}$	10
Matsui (2009)	Ward	0.15	0.14	$2.5 V_{r\infty}$	10
		0.15	0.65	5.5 $V_{r\infty}$	
Zhou et al. $(2016)$	Ward	0.5	1.2 to 1.6	$45-80m/s$	NA
Natarajan & Hangan (2010)	WindEEE	0.4	$\overline{0.5}$	$6.0 V_{\text{row}}$	16

 $Table 2.6.$  Results of the laboratory  $TUCs$ 



Table 2.6 (Cont.)

Razavi and Sarkar (2016)	ISU	1.8	0.78	<b>NA</b>	22
Natarajan (2012)	WindEEE	0.4	0.28 0.5	5.5 $V_{r\infty}$ $6.0 V_{\text{row}}$	16
Refan (2014)	WindEEE	0.35	1.29	2.3 $V_{\text{ro}}$	16
Tang et al. (2016)	<b>VORTECH</b>	4.0	$0.13$ to $0.6$	$2$ V <sub>r<math>\infty</math></sub> to 2.6 $V_{r\infty}$	10
Tang et al. $(2017)$	<b>VORTECH</b>	4.0	$0.17$ to 0.84	2 $V_{\text{res}}$ to 3 $V_{\text{res}}$	10

Table 2.7. Summary of laboratory tornado simulators



## **2.10. Analytical tornado vortex techniques**

The analytical tornado vortex techniques model the tornado at every instant of time by a mathematical equation. The most frequently used analytical models for tornado modeling are the RCVM, Burger-Rotts (BR), and Sullivan models as discussed by Strasser and Selvam (2015). These models are briefly discussed in the following sections.

## **2.10.1. Rankine combined vortex Model (RCVM)**

This model divides the vortex into two parts (Wilson, 1977): the inner part of the vortex which is in solid body rotation and the outer part of the vortex in which the  $V_{\theta}$  is a decreasing function of radius, as shown in Figure 2.12. The RCVM represents the air flow around a tornado with only the



 $V_{\theta}$  component, which implies that that the radial and axial velocity components are not included in this model (Lewellen, 1976).

Maxworthy et al. (1985), Vatistas (1989), Selvam (1985, 1993) and Selvam and Millett (2003) used RCVM for simulating the tornado-like vortices for flows over cubes. Brown and Wood (2011), Wurman (2002), Wurman and Gill (2000) compared Doppler velocity data from tornadoes with RCVM and concluded that the results of all model were in good agreement with the actual measurements. Xu and Hangan (2009) modeled the tornado-like vortex by using a free narrow jet solution combined with RCVM. The advantage of their model is that the upward free-jet can represent the two-dimensional radial and axial motions. Therefore, together with the V $\theta$  profile of the RCVM, this model provides three velocity components for the tornado-like vortices. Selvam and Gorecki (2012) used RCVM model to study the influence of the different ratios of tornado sizes to the cylinder size on the tornado forces. Strasser and Selvam (2015), Strasser, Yousef and Selvam (2016) and Dominquez and Selvam (2016) used this model to study the interaction of tornados with structures and hills. Also, Ahmed and Selvam (2015) used RCVM to investigate the ridge effects on the tornado path deviation and Yousef (2017) employed this model to investigate the tornado interaction with the dome buildings.

An advantage of the analytical models is they are easy to implement, and they only require two values to be defined in the model, namely the radius of the location and the tangential velocity (Selvam and Millett, 2003 and 2005). However, discontinuity of the velocity derivatives at the point of transition from free forced mode to forced, and also the overestimation of the velocity near the core are the shortcomings of the Rankine models. In addition, the RCVM overestimates the velocity near the core (Refan, 2014).





Figure 2.12. Rankine combined vortex model (RCVM)

#### **2.10.2. The Burgers-Rott (BR) vortex**

This model is an exact solution to the Navier-Stokes (NS) Equation. the BR vortex has a central axis similar to RCVM, around which is an azimuthal flow, as shown in Figure 2.13. Unlike the RCVM, the BT model has radial and axial velocity components as well. In addition, unlike the RCVM, there is partially an actual counterpart for this model in the atmosphere, as it results from suction at great height above a plane surface. Xu and Hangan (2009) compared the values of the actual tornados with the BR model and showed that this model produced similar results in four out of five locations.

However, the BT model suffers from some deficiencies. In the BR model, the axial velocity is constant with radius, but linear with height, which means that the vertical velocity is only a function of z but not x, which implies that the velocity field is similar everywhere (Varistas, 1989). Furthermore, modeling turbulence effect in this model is problematic (Lewellen, 1974) since when the viscosity is included, the partial differential equations of the NS equations will exhibit a diffusive behavior (Kilty, 2005). In addition, the vertical pressure gradient increases by height without bound, whereas it is negligible close to the ground. Therefore, BR is not a good model for finding the close-to-ground velocity (Refan, 2014).





Figure 2.13. The BR vortex model (Kilty, 2005)

## **2.10.3. Sullivan vortex model**

Similar to the BR model, the Sullivan vortex is also an exact solution to the NS Equation and has similarities to the BR model, as shown in Figure 2.14. The Sullivan vortex describes the flow in an intense tornado with a central downdraft, and localizes its updraft to a particular place. However, placing the vortex at the center of the updraft makes the model too symmetric to describe a real tornado. Furthermore, the Sulivan model is poor in presenting the  $V_{\theta}$  profile (Tang et al., 2016 and 2017). In addition, the minimum reported elevations using analytical models are almost 50m (Wen, 1975; Karstens et al., 2010).



Figure 2.14. Sullivan vortex model (Kilty, 2005)



#### **2.10.4. Lamb-Ossen vortex model**

Lamb-Ossen vortex mode represents a solution to the laminar NS Equations with axisymmetric solution for the swirl velocity together with the assumption that the axial and radial velocities are zero (Tryggeson, 2007). Strasser, Yousef and Selvam (2016) used the Lamb-Oseen model or the variant of Vatistas model to study the dynamic amplification of tornado wind field for a circular cylinder. One of the drawbacks of this model is that it considers radial and vertical velocity to be zero as a start and reports high  $V_{\theta}$  magnitude close to the ground.

### **2.11. CFD tornado chamber models**

In general, the CFD tornado chamber models are the representation of the experimental TVCs in a computational domain. In this regard, some CFD studies modeled the Ward-type simulator, such as Wilson and Rotunno (1986), Lewellen et al. (1997, 2005), Liu and Ishihara (2012, 2013, 2014), and Dominguez and Selvam (2017), some other studies simulated the ISU model in computer, such as Sarkar et al. (2005), Gallus et al. (2006) and Kuai et al. (2008). The former computational domain is called open outlet, and the latter is called semi-open outlet, which are shown in Figures 2.15 and 2.16, respectively. The semi-open outlet is mostly used for either considering the translation effect of the tornados or investigating the tornado interaction with a building inside the model, such as Phuc et al. (2012).





Figure 2.15. The computational model with open outlet. It is based on Ward-type simulator.



Figure 2.16. The computational model with semi-open outlet. It is based on ISU simulator.

## **2.11.1. Investigation of the tornado parameters by the CFD chamber models**

Wilson and Rottuno (1986) proposed models with  $S~0.3$  and  $r_0 = 1.0$ km. The constant  $r_0$  and small S parameter are shortcomings of their models. Lewellen et al. (1997 and 1999) investigated the influence of S value on tornado intensification near the surface by using LES, and reasonably captured the turbulent effects. Afterward, Lewellen et al. (2008) and Lewellen (2012) used CFD with a focus on improvement of the MGSs, for  $r_0 = 1.0$ km. They also showed that the core radius



 $(r_c)$  increases by increase of the S parameter. However, they only considered  $r_o=1.0$ km, and did not take into account of the effect of variation of ro. Moreover, the minimum attainable elevation is almost 27m AGL in the studies of Lewellen et al. (Table 2.8).

Also, Ishihara et al. (2011) and Liu and Ishihara (2013) used CFD models with constant  $r_0$ =150mm, capable of producing actual  $r_0$  radii of up to 1.0km. However, the S parameter was less than 1.0. Liu and Ishihara (2012) used a similar model with the same size but capable of producing  $S~3.8$ . However they did not present the effect of high S values on V $_{\theta}$ . Likewise, Liu and Ishihara (2016) used the same model and added the roughness effect. Although their models are capable of capturing spacing of 1.0m close to the ground, their models are limited to  $r_0 = 1.0$ km (Table 2.8). Phuc et al. (2012) used  $r_0$ =0.3m and S=0.68 to determine the relation of the aspect ratio to the pressure coefficients, but did not report the velocity wind-field. Zhao et al. (2017) used the largest  $r_0$  equal to 800m, but their focus was on variation of the H<sub>o</sub> rather than the  $r_0$  (Table 2.8). Natarajan and Hangan (2012) used S=0.5 and 2.0 with  $r_0=H_0=0.4$ m, and Natarajan (2012) proposed a model with S~0.3 and r<sub>o</sub>=1.0km to investigate the effect of variation of the S value on the V<sub>θ</sub> profile. However, the minimum attainable elevation in their models is 20m AGL. In addition, the constant  $r<sub>o</sub>$  and small S parameter are shortcomings of their models (Table 2.8). Hangan and Kim (2008) proposed a 3D numerical model for TVCs to investigate dependency of the  $V_{\theta}$  of actual tornados on the S and the relation with Fujita scale. They used S in the range of 0.28 to 2.0 and investigated the 1998 Spencer tornado. However, they only considered  $r_0 = 1.0$ km which is the radius of the 1998 Spencer tornado. Gallus et al. (2006) and Kuai et al. (2008) utilized models with ro= 800m  $r_0$ =1000m and  $r_0$ =1100m, which correspond to the  $r_0$  of actual tornados. Also, they used S parameter in the range of 0.17≤S≤0.26, and conducted parameter sensitivity tests for the mesh size,



boundary conditions and surface roughness. However, the limitation of their study is small range of S and ro.

#### **2.11.2. Summary of the CFD models**

Table 2.8 presents a summary of the CFD parameters. It can be seen that the CFD models suffer from limited range of the r<sub>o</sub> and S parameters. The CFD models are limited to the r<sub>o</sub> $\leq$ 1.0km, whereas the actual is up to 3.0km. In addition, in the CFD models, S is mostly less than 1. In addition, the minimum elevation attainable in the CFD studies is 6m (Liu and Ishihara, 2012, 2013, and 2014). Hence, the existing CFD studies cannot evaluate the  $V_{\theta}$  profile in the elevation of the typical buildings (z=3.3m).

Reference	$r_o(km)$	Swirl ratio	$V_{\theta, max}$	Minimum z (m)
Wilson and Rotunno (1986)	1.0	0.3	$4.99V_{r\infty}$	20
Wicker and Wilhelmson (1993)	1.0	<b>NA</b>	32m/s	20
Lewellen et al. (1997)	1.0	0.94	$6.6 V_{r\infty}$	27
Lewellen et al. (2005)	1.0	0.94	$6.5 V_{r\infty}$	27
Sarkar et al. (2005)	0.46	0.17	4.4 $V_{r\infty}$	20
Kuai et al. (2008)	$0.8$ and 1.0	0.17	4.4 $V_{r\infty}$	20
Hangan and Kim (2008)	0.4	0.28	$3.75V_{r\infty}$	20
Ishihara et al. (2011)	1.5	0.31	NA	10
Liu and Ishihara (2012)	1.5	NA	NA	10
Liu and Ishihara (2013)	1.5	0.6	15.3m/s	10
		3.8	24m/s	
Liu and Ishihara (2014)	1.5	<b>NA</b>	<b>NA</b>	10

Table 2.8. Results of CFD tornado chamber models on the  $V_{\theta}$  profiles



$   -$ Reference	$r_0(km)$	Swirl ratio	$V_{\theta, max}$	Minimum z (m)
Natarajan (2012)	0.4	0.28	$5.5~V_{r\infty}$ - 7.5 $V_{r\infty}$	NA.
Zhao et al. $(2017)$	0.8	< 1.0	$3 V_{r\infty}$ to 4 $V_{r\infty}$	<b>NA</b>
Tao Tao et al. (2017)	NA	<b>NA</b>	26m/s 25m/s	<b>NA</b>
Dominguez and Selvam (2017)	1.0	0.6	4.98 $V_{r\infty}$	

Table 2.8. (Cont.)

## **2.12. Criteria of comparing the tornado simulations to the actual tornados**

## **2.12.1. Significance**

The main parameters of the laboratory and CFD models are the Re, S and ro. Using high value of R<sup>e</sup> makes the simulation results independent of Re. Thus, the simulation results rely heavily on S and ro. Hence, the laboratory and CFD models report the flow characteristics by the S parameter, which is directly related to the  $V_{\theta}$  and indicates the intensity of tornados. However, the S parameter is very difficult to determine in actual tornados because there is no clear definition of the inlet/outlet boundary conditions in the actual tornados (Refan, 2014). Therefore, comparing criteria should be defined to compare the simulation results to the actual tornados. These criteria should be measurable geometric scales. There are various geometric lengths in a tornado simulator such as updraft radius, inflow depth, rc and z<sub>max</sub>. After determining the proper criteria, the velocity fields can be matched with the numerical simulations.



#### **2.12.2. Defining the comparison criteria**

Baker and Church (1979) used the average velocity as the comparison criteria and called it as length scale. However, Nolan (2012) showed that this length scale is not accurate for small tornados. Mishra et al. (2008) used  $r_c$  as length scale using the TTU simulator for the 1998 Spencer tornado. They also added that the radial profile of the  $V_{\theta}$  at various heights can be used for comparison of the simulations to actual tornados. Haan et al. (2008) validated the ISU simulator through comparisons between full-scale and simulator flow fields of Spencer and Mulhall tornados. They used tornado structure, and the radial  $V_{\theta}$  profiles as a comparison criterion. In other words, they compared the radial  $V_{\theta}$  profiles of their simulations at different heights to the in-field measurements and observed that they collide perfectly on each other. They concluded that the r<sup>c</sup> and the  $z_{\text{max}}$  are the two important comparison criteria. Zhang and Sarkar (2012) used Particle Image Velocimetry (PIV) to compare the V $_{\theta}$  profile of the simulated tornado with that of an actual tornado using the  $V_{\theta,\text{max}}$  and  $r_c$  as comparison criteria. Kuai et al. (2008) employed a CFD model and used  $V_{\theta, max}$  and r<sub>o</sub> as the criteria to compare the simulation results to the radar data. They used the radial V<sub>θ</sub> profile and the V<sub>θ,max</sub>, r<sub>c</sub> and z<sub>max</sub> as the comparison criteria. Similarly, Refan (2014), and Refan et al. (2017) used the GBVTD to determine intensity of the actual tornados and for this purpose they used the r<sup>c</sup> and zmax as the comparison criteria for their comparison. Therefore, reviewing the previous studies shows that the structure,  $r_c$  and  $z_{\text{max}}$  of tornados are proper criteria for comparison of the simulations to the actual tornados.

## **2.13. Summary of the chapter**

Review of the previous studies on the tornado effects on buildings indicates that the infield and post-damage investigations are not capable of evaluating the  $V_{\theta}$  profile close to the ground. On the other hand, the laboratory TVCs, despite being able to model the tornados, are limited to minimum



elevation of 35m AGL and certain  $r_0$  lengths. The analytical vortex models cannot evaluate the V $_\theta$ profile at less than 50m AGL. In parallel, although the CFD models can model tornados for 0.2≤S≤3.6, they are limited to r<sub>o</sub>≤1.0km. In addition, the CFD models, cannot evaluate the V<sub>θ</sub> profile at z=3.3m, which is the elevation of the typical buildings. Moreover, review shows that the r<sup>o</sup> of the most intense tornados in the USA is in the range of 0.7km to 2.3km.



#### **CHAPTER 3. RESEARCH METHODOLOGY**

In this chapter, the methodology employed in the study is given. The main reason for using CFD technique in this study is that, unlike the laboratory models, the CFD techniques provide full access to wind field as well as allowing a control of important simulation parameters without compromising the accuracy of the simulation. The Navier Stokes (NS) equations for the incompressible flow were approximated by Finite Volume Method (FVM), which was found to be more efficient than Finite Element Method (FEM) for the tornado modeling purposes (Selvam, 1994). The turbulence is modeled by Large Eddy Simulation (LES), which is ideally a proper technique for the strong short-term vortices of tornados (Lim et al., 2009).

## **3.1. Governing Equations**

The governing equations in cylindrical coordinates system using LES for axisymmetric model are obtained by filtering the time dependent NS equations as follows (Stein and Harlow, 1974):

The continuity equation is:

$$
\frac{1}{r}\frac{\partial}{\partial r}(r.V_r) + \frac{\partial}{\partial z}V_z = 0\tag{3.1}
$$

The r-component of momentum equation is:

$$
\frac{\partial V_r}{\partial t} + \frac{1}{r} \frac{\partial r V_r^2}{\partial r} + \frac{\partial V_r V_z}{\partial z} = -\frac{\partial p}{\partial r} + \left[ 2v_{eff} \frac{\partial^2 V_r}{\partial r^2} + \frac{2}{r} v_{eff} \left( \frac{\partial V_r}{\partial r} - \frac{V_r}{r} \right) + \frac{\partial}{\partial z} v_{eff} \left( \frac{\partial V_r}{\partial z} + \frac{\partial V_z}{\partial r} \right) \right] + \frac{V_\theta^2}{r} (3.2)
$$

The  $\theta$ -component of momentum equation is:

$$
\frac{\partial V_{\theta}}{\partial t} + \frac{1}{r} \frac{\partial r V_{r} V_{\theta}}{\partial r} + \frac{\partial V_{\theta} V_{z}}{\partial z} = -\frac{V_{r} V_{\theta}}{r} + \left[ 2v_{eff} \frac{\partial^{2} V_{\theta}}{\partial z^{2}} + \frac{\partial}{\partial r} v_{eff} \left( \frac{\partial V_{\theta}}{\partial r} - \frac{V_{\theta}}{r} \right) + \frac{2}{r} v_{eff} \left( \frac{\partial V_{\theta}}{\partial r} - \frac{V_{\theta}}{r} \right) \right] (3.3)
$$

$$
\lim_{\omega\to 0}\mathbf{Z}\log\mathbf{Z}
$$

The *z*-component of momentum equation is:

$$
\frac{\partial v_z}{\partial t} + \frac{1}{r} \frac{\partial r v_r v_z}{\partial r} + \frac{\partial v_z^2}{\partial z} = -\frac{\partial p}{\partial z} + \left[ 2v_{eff} \frac{\partial^2 v_z}{\partial z^2} + \frac{1}{r} \frac{\partial}{\partial r} v_{eff} \left( r \left( \frac{\partial v_r}{\partial z} - \frac{\partial v_z}{\partial r} \right) \right) \right] \tag{3.4}
$$

In which

 $v_{eff} = v + v_{sgs}$ 

And  $v_{sqs}$  is calculated as follows (Barhaghi and Davidson, 2003):

$$
v_{sgs} = (C_s \nabla)^2 f_\mu \sqrt{2. s_{ij} . s_{ij}}
$$

Where  $C_s = 0.1$ , and

$$
f_{\mu} = 1 - \exp(-\frac{y^{*}}{25})
$$
  
\n
$$
2. s_{ij}. s_{ij} = 2 \left[ (\frac{\partial V_{r}}{\partial r})^{2} + (\frac{1}{r} \frac{\partial V_{\theta}}{\partial \theta} + \frac{V_{r}}{r})^{2} + (\frac{\partial V_{z}}{\partial z})^{2} \right]
$$
  
\n
$$
+ \left[ (\frac{\partial V_{r}}{\partial z} + \frac{\partial V_{z}}{\partial r})^{2} + (\frac{1}{r} \frac{\partial V_{r}}{\partial \theta} + \frac{\partial V_{\theta}}{\partial r} - \frac{V_{\theta}}{r})^{2} + (\frac{\partial V_{\theta}}{\partial z} + \frac{1}{r} \frac{\partial V_{z}}{\partial \theta})^{2} \right]
$$

The governing equations are non-dimensionalized using  $V_{r_{\infty}}$  and  $H_0$  as the reference values. The reference value for H<sub>o</sub> and V<sub>r∞</sub> are considered to be 1.0km and 1.0 m/s, respectively. For these reference values the  $R_e$  will be  $1x10^8$ .

## **3.2. Computational domain and boundary conditions**

The computational domain used in this study is similar to the computational domain of Lewellen et al. (1997). Their computational domain is a Ward-Type TVC of 1km x 2km domain, which means that the updraft radius (r<sub>o</sub>) and the domain height (h=2H<sub>o</sub>) are respectively 1.0km, 2.0km, and the inlet height  $(H<sub>o</sub>)$  is 1.0km. considering  $H<sub>o</sub>=1.0km$  as reference value, therefore the



nondimensional computational domain is  $1.0x2.0$  (r<sub>o</sub>=H<sub>o</sub> & h=2H<sub>o</sub>). However, the present study uses a similar domain with the only difference of using various r<sup>o</sup> from 0.7km to 2.3km. Therefore, the nondimensional  $r_0$  varies from 0.7 to 2.3 The increment of  $r_0$  is 0.1, which means that  $r_0$  will be 0.7, 0.8, 0.9 and so on. Nondimensional  $H_0$  is 1.0 and h=2 $H_0$  in this study. The boundary conditions of the axisymmetric model are similar to study of Wilson and Rotunno (1986) as shown in Figure 3.1 and Table 3.1.



Figure 3.1. Axisymmetric computational domain and the boundary conditions

Region	Boundary type	<b>Boundary Condition</b>	Region	Boundary type	<b>Boundary Condition</b>
AB	Axisymmetric line	$\frac{\partial V_z}{\partial r} = \frac{\partial P}{\partial r} = 0.0$ $r = V_r = V_\theta = 0.0$	DE	Inlet	$V_{r\infty}$ $V_{\theta}$ $V_z = 0.0$
<b>BC</b>	Outlet	$P_n = V_{r\infty} = V_\theta = \frac{\partial V_z}{\partial r} = 0.0$	EA	Ground	$P_z = V_{r\infty} = V_{\theta} = V_z = 0.0$
CD	Wall	$V_{r\infty} = V_{\theta} = V_{z} = 0.0$			

Table 3.1. Boundary conditions of the model



## **3.3. Wall function**

For the cells close to the ground of the TVC and to the symmetry line, the Law of the Wall is used in the modeling. In this technique, the turbulence near that boundary is a function of only the flow conditions pertaining to that wall and is independent of the flow conditions further away. Law of the Wall is derived and applied using Equations (3.5) to (3.7) taken from Neale et al. (2006). For the distance of *y* from the wall, the friction velocity  $u_r$  can be defined as:

$$
u_r = \sqrt{\tau_w / \rho} \tag{3.5}
$$

Where  $\tau_w$  is the wall shear stress, and is based on the velocity gradient in the direction normal to the surface of the wall (Neale et al., 2006):

$$
\tau_w = \rho v \frac{\partial v_r}{\partial y} \tag{3.6}
$$

Where the dimensions of the parameters are:  $y[L], V_r(y)[L/T], \tau_w [M/LT^2], \rho [M/L^3], v[L^2/T]$ . The dimensionless length and velocity are, respectively:

$$
y^* = \frac{u_r y}{v}
$$
  

$$
V_r^+ = \frac{v_r}{u_r}
$$
 (3.7)

#### **3.4. Radial and tangential velocity components**

 $V_{r_{\infty}}$  is assumed to vary logarithmically from the ground at the inlet and the equation for the radial velocity is as follows:

$$
V_r = C_1 \ln \frac{z + z_0}{z_0} \tag{3.8}
$$

For open country or Exposure C taking zo=0.035m, the nondimensional z<sub>o</sub> will be 0.035/1000=3.5x10<sup>-5</sup>. Keeping the maximum  $V_{r_{\infty}}=1.0$  m/s at z=Ho, the corresponding C<sub>1</sub> becomes:



$$
C_1 = \frac{V_{r\infty}}{\ln \frac{H_0 + z_0}{z_0}} = 0.0975
$$

Knowing  $V_{r_{\infty}}$ , then V $\theta$  is obtained at the inlet by rearranging Equation (1.3) as follows:

$$
V_{\theta} = \frac{s(2H_0)V_{r\infty}}{r_0} \tag{3.9}
$$

In Equation 3.9, the  $V_{r_{\infty}}$  and  $H_0$  are constant, and the two parameters of S and  $r_0$  will be varied to determine the  $V_{\theta}$ .

## **3.5. Grid resolution of the computational domain**

Dominguez and Selvam (2017) used the same domain as that of Lewellen et al. (1997) but used MGS=0.001H<sup>o</sup> alongside the r- and z- axes. The present study also uses MGS=0.001H<sup>o</sup> along the r- and z-axis in the vicinity of the axisymmetric line (z axis). Considering  $H<sub>o</sub>=1.0km$  for nondimensionalization, thus the model can capture 1.0m spacing close to the axisymmetric line. In addition, the grid spacing exponentially increases by 1.1 from the center of the tornado and the maximum spacing is limited to 0.1H<sub>o</sub>. Figure 3.2 shows the computational domains of  $r_0$ =0.7km, 1.0km, 1.5km and 2.0km using MGS=0.001Ho. As can be seen in this figure, more refinement is applied near the ground and near the z-axis in order to properly capture the boundary layer. This refined grid close to ground enables the model to evaluate the  $V_{\theta}$  in the vicinity of the ground. Figure 3.3 shows the zoomed view close to the symmetry line of the computational domain, and it can be seen that the spacing of 1.0m is captured close to the ground. The number of nodes for different r<sub>o</sub> are given in Table 3.2. Table 3.3 summarizes the physical and mesh parameters of the numerical tornado simulator.





Figure 3.2. Computational domains with MGS=0.001H<sub>o</sub> for: a)  $r_0$ =0.7km; b)  $r_0$ =1.0km; c)  $r_0 = 1.5$ km; d)  $r_0 = 2.0$ km



Figure 3.3. a) Computational domain for  $r_0$ =1.0km; b) Zoomed view of the high resolution close to symmetry line; c) Zoomed view of the high resolution which captures 1.0m spacing close to the symmetry line.



Radius $(ro)$	Number of nodes in the computational domain	Radius $(ro)$	Number of nodes on the computational domain
0.7km	46x60	1.6km	56x60
0.8km	48x60	1.7km	57x60
0.9km	49x60	1.8km	58x60
1.0km	50x60	1.9km	59x60
1.1km	51x60	2.0km	60x60
1.2km	52x60	2.1km	61x60
1.3km	53x60	2.2km	62x60
1.4km	54x60	2.3km	63x60
1.5km	55x60		

Table 3.2. Number of nodes in computational domain with  $MGS=0.001H_0$ 

Table 3.3. Physical parameters and mesh parameters of numerical tornado simulator

Parameter	Actual value	Nondimensional	Parameter	Actual	Nondimensional
		value		value	value
Domain height (h)	2000 <sub>m</sub>	2.0	Reynolds number	1.e8	1.e8
H <sub>o</sub>	1000m	1.0	$V_{r\infty}$	$1.0 \text{ m/s}$	1.0
$r_{\rm o}$	$700m -$ 2300 <sub>m</sub>	$0.7 - 2.3$	<b>MGS</b>	$0.001H_0$	0.001

### **3.6. Solution scheme**

The CFD model uses the SOLA-Yaqui type algorithm to solve the equations (Hirt et al., 1975). In this method, a staggered grid is used where velocities are stored at the nodes and the pressure at the middle of the cell. In the momentum equation, the diffusion and convention terms are respectively implicit and explicit. The equations are approximated using second order FVM. At this time, the pressure is solved using SOLA type pressure correction. The advantage of using the Yaqui-type configuration is to avoid the problem of pressure-velocity decoupling (Harlow and Welch, 1965; Selvam, 1992). The computer model is run for 5 time units with a time step of 0.1 to satisfy the CFL condition.



## **3.7. Running the program**

The program used for this simulation was developed at the Computational Laboratory of the Civil Engineering Department at University of Arkansas, and is called **Axisym6**. The program is developed with FORTRAN language, is run in LINUX terminal on the server of the Computational Mechanics Lab (CML) of the University of Arkansas. Each simulation takes 60 minutes to 150 minutes depending on the size of the domain.

## **3.7.1. Program input**

The SSH Secure File Transfer is used to connect to the server and to run the program in LINUX environment. A sample program input is shown in Table 3.4 and Figure 3.4. In the program input, XMAX refers to the r<sub>o</sub> and S refers to the swirl ratio. The input is given to the program using \*.txt file. In this study, the  $H<sub>o</sub>=1000m$  and is constant.

raoic 5.4. Data mpat of the AMByllio program for $10-1.0$ Km and $5-1.0$	
Definition	Value
	(non-dimensional)
Minimum grid spacing (MGS)	0.001
Maximum grid spacing	0.1
growth factor of the spacing	1.1
Radius of the domain (tornado radius, $r_0$ )	0.7
Height of the domain (h)	2.0
Time spacing	0.01
Reynolds number	1.e8
Swirl ratio	1.0
Total computation time unit	5.0

Table 3.4. Data input of the **Axisym6** program for  $r_0 = 1.0$ km and  $S = 1.0$ 



```
axisy-i - Notepad
                                                                                     \Box\timesFile Edit Format View Help
.001, 0.1, 1.1, 1.0, 2.0, 0.01, 1.e8, 2.0, 5.0
READ(4,*)HMIN, HMAX, FAC, XMAX, ZMAX, DT, REN, S, TTIME
c.....GENERATE GRID IN X, Y & Z
        HMTN = 0.001c
        HMAX = .1\epsilonFAC=1.1\epsilonXMAX = 1.0\epsilon\bar{\mathsf{C}}ZMAX=2.0c
        DT = 0.01REN=1.d8
c
        S=0.\mu -this S is twice the swirl ratio value & Vr=1.0=Ho=ro,
\mathsf{c}\epsilonTTIME=5.0
```
Figure 3.4. Data input of the **Axisym6** program for  $r_0 = 1.0$ km and S=1.0

#### **3.7.2. Post-processing**

The output of the program for each run is stored in \*.plt file which can be opened in TECPLOT software. The results include the pressure (p) and  $V_{\theta}$  at different (r,z) points of the domain.

A program, called the **velc** program is used to plot the radial and vertical velocity profiles at different heights. The **velc** is written in FORTRAN. The input of the **velc** program is the output of the **Axisym6** program. Table 3.5 and Figure 3.5 show an input sample of the **velc** program for ro=1.0 at z=51.5m. Input of Table 3.5 shows that nine files from **Axisym6** are used as input for **velc**. Each of these nine files correspond to a certain S value. The **velc** program plots the profile at node=28. This node corresponds to  $z=51.5m$  for  $r_0=1.0km$ . in order to plot the velocity profiles at a certain distance from the tornado center, the same program can be used. In this case, instead of using the node number in the desired elevation, the number of node in the desired radial location should be used as input. The results are stored on a \*.plt file and are thus displayed in TECPLOT.



Program inputs	Value
Number of nodes in X direction	50
Number of nodes in Y direction	60
Number of input files	
Node corresponding to desired elevation	28

Table 3.5. Sample input of **velc** for  $r_0 = 1.0$ km at  $z = 51.5$ m

velc1 - Notepad		П	×
File Edit Format View Help			
50,60,9,28 3.plt 4.plt 5.plt 6.plt 7.plt 8.plt 9.plt $10.$ plt $12.$ plt			
$\,<$			$\!>$

Figure 3.5. Sample input of **velc** program for r<sub>o</sub>=1.0km at z=51.5m

# **3.8. Verification of the simulations**

Simulation results are verified against the radar measurements of actual tornados. For verification purpose, the comparison criteria defined in Section 2.12 are employed, which include the vertical structure, r<sub>c</sub>, z<sub>max</sub>.

# **3.8.1. Assumptions made for comparison of the simulations to the radar measurements**

In order to verify the simulation results against the radar measurements of actual tornados, the following assumptions are made:

1. Only actual tornados for which radar measurements of ro, rc, zmax are available are considered for comparison.



- 2. The  $r<sub>o</sub>$  of actual tornados, taken from radar measurements, are used in the simulation; the results are then compared to the data collected from actual tornados.
- 3. Only actual tornados with the radii in the range of 0.7km to 2.3km are considered for comparison. As shown in Table 2.5, actual tornados with  $r_0 < 0.7$ km are of less significance in terms of intensity and damage and are thus excluded. Similarly, the largest tornado r<sup>o</sup> in the USA is the EL Reno tornado of 2013 with  $r_0 = 2.3$ km.

## **3.9. Summary of the chapter**

In this chapter, the governing equations using LES for axisymmetric model, and subsequently, the computational domain and the boundary conditions were presented. Finally, verification criteria were proposed.



# **CHAPTER 4. INVESTIGATION OF THE EFFECT OF VARIATION OF THE R<sup>O</sup> ON THE MAXIMUM V<sup>θ</sup>**

Jischke and Parang (1974) and Church et al. (1979) asserted that the  $V_{\theta, max}$  is dependent on the S parameter, and variation of the S parameter affects the  $r_c$  and  $z_{\text{max}}$ . In this chapter, initially the S parameter producing the  $V_{\theta, max}$  will be determined for different r<sub>o</sub> radii, and then the effect of variation of the S parameter on the vertical and radial  $V_\theta$  profiles of different  $r_\theta$  will be investigated. Afterwards, the effect of variation of the S parameter on the vertical structure of the tornados is studied.

## **4.1. Swirl ratio corresponding to the Touchdown and Vθ,max for different r<sup>o</sup> radii**

Previous studies show that changing the r<sub>o</sub> will affect the swirl ratios of tornado touchdown and the V<sub>θ,max</sub>. However, swirl ratios of touchdown and the V<sub>θ,max</sub> are not investigated for different r<sub>o</sub>. In this regard, the S parameter of touchdown is the S at which the tornado initially touches the ground, whereas the S of the V $_{\theta,\text{max}}$  is the S after touchdown which produces the highest intensity. Review of the previous laboratory and CFD tornado simulators in Tables 2.7 and 2.8 of the present study shows that the  $V_{\theta,\text{max}}$  occurs at S value is in the range of 0.2 to 1.5. Therefore, the present study uses 0.2≤S≤1.5 for each r<sub>o</sub> to investigate their wind-fields Therefore, the swirl ratios that produce the touchdown and the  $V_{\theta, max}$  are determined.

## **4.1.1. Simulation results**

Figure 4.1 presents the S parameters corresponding to the touchdown and  $V_{\theta,\text{max}}$  for various  $r_0$ radii. It can be seen in Figure 4.1 for  $r_0$  from 0.7km $\le r_0 \le 1.0$ km, the touchdown occurs at S=0.40; for r<sub>o</sub> $\geq$ 1.0km the touchdown S gradually increases from 0.4 to 0.7 at r<sub>o</sub>=1.9km. Likewise, for  $r_0 \geq 2.0$ km the touchdown S is in the range of 0.7 to 0.9.



Figure 4.1 also shows the S values that correspond to the  $V_{\theta, max}$  for different  $r_0$  radii. It can be seen in this figure that for  $0.7 \text{km} \leq r \leq 1.5 \text{km}$ , the V $\theta_{\text{t,max}}$  occurs at almost  $0.50 \leq S \leq 0.60$ . Occurrence of the  $V_{\theta, max}$  in this range was observed by Ishihara (2016) for a limited number of r<sub>o</sub> radii. For r<sub>o</sub>≥1.5km, the S value associated with  $V_{\theta, max}$  increases with the r<sub>o</sub> lengths and for r<sub>o</sub>=2.3km the S of the V<sub> $\theta, max$ </sub> is 1.3. Figure 4.1 also shows that the S of the  $V_{\theta, max}$  is not similar to the touchdown S, rather it is larger than the touchdown S. In addition, this difference gradually increases after  $r_0 \ge 1.9$ km. Using the information given in Figure 4.1, the  $V_{\theta, max}$ , r<sub>c</sub> and  $z_{max}$  can be investigated.

## **4.1.2. Summary of findings**

Simulation results show that by increasing the ro, the S of touchdown and the S that produces the  $V_{\theta, max}$  will increase. In addition, the S parameter producing the  $V_{\theta, max}$  is larger than the touchdown S. In other words, the  $V_{\theta, max}$  occurs beyond the touchdown.

#### **4.1.3. Comparison of the results to the CFD and laboratory results**

Figure 4.1 shows that for  $r_0 = 1.0$ km, the V $\theta_{\text{max}}$  occurs at S=0.6. Lewellen et al. (1997) and Ishiahara et al.  $(2011)$ , respectively, reported the S=0.60 and S=0.65 as the S value corresponding to the  $V_{\theta, \text{max}}$ . Therefore, the results of the present study for r<sub>o</sub>=1.0km is in agreement with the previous studies. Similarly, findings of this section on the touchdown S of the tornados complies well with Lewellen et al. (1999) that suggested by increasing the r<sub>o</sub>, the S that produces the V $_{\theta, \text{max}}$  is likely to increase. Likewise, Church et al. (1979) and Jischke and Parang (1974) reported the touchdown S equal to 0.5. Refan (2014), Refan and Hangan (2016) and Refan et al. (2017) reported the touchdown at approximately S=0.57. Also, the CFD model of Hangan and Kim (2008) reported that at S=0.4 the cell vortex breakdown is observed, and at S=0.7 touchdown completely occurs. However, they did not investigate any S value between 0.4 to 0.7, rendering that the touchdown S should be in the range of  $S=0.4$  to  $S=0.7$ .





Figure 4.1. Swirl ratios corresponding to the touchdown and  $V_{\theta,\text{max}}$  for 0.7km≤r<sub>o</sub>≤2.3km

## **4.2.**  $V_{\theta, \text{max}}$ ,  $r_c$  and  $z_{\text{max}}$  for different  $r_o$

In this chapter, the  $V_{\theta, max}$ , r<sub>c</sub> and z<sub>max</sub> of different tornado radii are reported using the S that produces the V $_{\theta,\text{max}}$ . The S producing the V $_{\theta,\text{max}}$  was reported in Figure 4.1.

#### **4.2.1. Absolute Vθ,max for various r<sup>o</sup>**

Figure 4.2 presents the absolute  $V_{\theta,\text{max}}/V_{r_{\infty}}$  for various tornado with 0.7km≤ro≤2.3km. The

 $V_{\theta, max}/V_{r\infty}$  is yielded at the S parameter given in Figure 4.1. It can be seen in Figure 4.2 that the  $V_{\theta,\text{max}}/V_{r\infty}$  occurs for r<sub>o</sub>=0.7 (V $_{\theta}$ =6.53V<sub>r∞</sub>). However, by increasing r<sub>o</sub> from 0.7km to 1.3km, the  $V_{\theta,\text{max}}/V_{r\infty}$  gradually reduces and for r<sub>o</sub>=1.3km, the V<sub> $\theta,\text{max}$ </sub> is 4.05V<sub>r $\infty$ </sub>. For 1.4km $\leq$ r<sub>o</sub> $\leq$ 1.9km, the V $\theta_{\text{max}}$  is almost 3.80V<sub>r∞</sub>, and for r<sub>o</sub>>1.9km the V $\theta_{\text{max}}$  again reduces to less than 3.50V<sub>r∞</sub>. So, it can be concluded that the V<sub>θ,max</sub>/V<sub>r∞</sub> is significant for 0.7km≤r<sub>o</sub>≤1.3km. Results of Figure 4.2 comply well with the previous studies. It can be seen in Figure 4.2 that for  $r_0 = 1.0 \text{km}$ , the highest



peak is  $V_{\theta, max} = 4.98 V_{\infty}$ . Wilson and Rotunno (1986) reported  $V_{\theta, max} = 5.0 V_{\infty}$  for r<sub>o</sub>=1.0km. In addition, Lewellen et al. (1997) reported the V $\theta_{\rm{max}}=6.6$  V<sub>r∞</sub>, which is in good agreement with the finding of the present study.

### **4.2.2.**  $V_{\theta, \text{max}}$  for various  $r_{\theta}$  radii at  $z=3.3$ m

As was stated in the first chapter, the  $V_{\theta}$  at less than 10m AGL is not reported in the previous CFD or laboratory chamber models. The present section reports the V<sub>θ,max</sub>/V<sub>r∞</sub> of different tornado radii at z=3.3m, which is the elevation of the typical buildings (Ishihara et al., 2011; Dominguez and Selvam, 2017). Figure 4.3 shows the V $_{\theta,\text{max}}/V_{\text{r}\infty}$  for various tornado radii at z=3.3m. It can be seen in Figure 4.3 that for r<sub>o</sub>=0.7km, the V<sub>θ,max</sub> is almost 2.5V<sub>r∞</sub>, while it constantly reduces to almost 1.0V<sub>r</sub> for r<sub>o</sub>=1.3km, and then reduces to almost  $0.6V_{r\infty}$  for r<sub>o</sub>≥2.1km. This finding implies that at  $z=3.3m$ , the effect of the intensity of the tornado reduces by increase of the tornado's  $r_0$ .

The reason of higher  $V_{\theta,\text{max}}/V_{\text{r}\infty}$  for smaller  $r_0$  lies in the amount of energy transferred to the tornado. Wilson and Rotunno (1986) stated that in small r<sub>o</sub> radii, a significant angular momentum will be carried to the smaller radii. This phenomenon is due to the narrowness of the swath of the tornado close to the ground for the smaller radii and thus the intensity is higher.





Figure 4.2. Absolute V $_{\theta, max}$  for different r<sub>o</sub> radii (V $_{\theta, max}$ /V<sub>r∞</sub>)



Figure 4.3. V $_{\theta, max}$  at z=3.3m for different r<sub>o</sub> radii (V $_{\theta, max}$ /V<sub>r∞</sub>)



#### **4.2.3. Zmax for different r<sup>o</sup> radii**

Figure 4.4 shows the  $z_{\text{max}}$  for different  $r_0$  radii. It can be seen in the figure that by increasing the  $r_0$ , the z<sub>max</sub> will also increase. However, for r<sub>0</sub> $\geq$ 2.0km, the z<sub>max</sub> is constant at z<sub>max</sub>=64m. This finding complies reasonably with the actual tornados. Wurman et al.  $(2013)$  reported  $z_{max}=27.5$ m with  $r_0$ =1.0km for Goshen Wyoming tornado of 2009. Figure 4.4 shows that for  $r_0$ =1.0km  $z_{\text{max}}$ =27m. Similarly, Hangan and Kim (2008) reported  $z_{\text{max}} = 20$ m for Spencer tornado which had  $r_{\text{o}} = 0.8 \text{km}$ and Figure 4.4 shows that for  $r_0 = 0.8 \text{ km}$ ,  $z_{\text{max}}$  is equal to 21m.

The reason of increase of  $z_{\text{max}}$  by increase of the  $r_0$  length is the outward expansion of the tornado vortex by increase of ro. In general, the vortex column is narrow close to the ground, but at the top of the vortex column, the vortex column is wider (Lewellen et al., 1997; Wurman and Grill, 2000; Wurman and Alexander, 2005). This phenomenon was observed in the in-field study of the actual tornados (Bluestein et al., 2015; Bluestein and Pazmany, 2000). Simulations also show this outward expansion of the tornado column by increase of the ro. Figure 4.5 compares the simulation results to the in-field measurements for the phenomenon.



Figure 4.4. z<sub>max</sub> for different r<sub>o</sub> radii (m)




Figure 4.5. The outward expansion of tornados with larger  $r_0$ . a)  $r_0=1.5$ km; b)  $r_0=1.8$ km; c) actual tornado with small radius; d) actual tornado with large radius

## **4.2.4. Core radius (rc) for different r<sup>o</sup>**

Figure 4.6 presents the  $r_c$  for different  $r_o$ . This figure shows the direct proportionality of the S to the r<sub>c</sub>. It can be seen in Figure 4.6 that for  $0.7 \text{km} \leq r_0 \leq 1.8 \text{km}$ , the r<sub>c</sub> is in the range of almost 100m to 180m. However, for  $r_0 > 1.8$ km, by increasing the  $r_0$ , the  $r_c$  also expands from  $r_c=222$ m at  $r_0 = 1.9$ km to  $r_c = 460$ m at  $r_0 = 2.3$ km.

Increase of the r<sub>c</sub> with increase of the r<sub>0</sub> is in agreement with experimental studies of Ward (1972), Davies-Jones (1973), Jischke and Parang (1974), Church et al. (1979), Church and Snow (1993),



Baker and Church (1979), Tari et al (2010), Refan (2014), Refan et al. (2017), Refan and Hangan (2017). Likewise, Hangan and Kim (2008) reported the  $r_c$  at S=0.7 and S=1.0 to be, respectively, 90m and 220m. Table 4.1 summarizes findings of the swirl ratio of touchdown and swirl ratio of  $V_{\theta, max}$ , the absolute  $V_{\theta, max}$ , the  $V_{\theta, max}$  at  $z=3.3$ m,  $z_{max}$ , and r<sub>c</sub>.



Figure 4.6. The core radius (rc) for different ro radii (m)

$r_o(km)$	Touchdown S	Table 4.1. Building y or the Hildings for unferent radii S of $V_{\theta, max}$	Absolute $V_{\theta, max}/V_{r\infty}$	$V_{\theta, max}/V_{r\infty}$ at $z=3.3$	$z_{max}(m)$	$r_c(m)$
0.7	$0.4\,$	0.5	6.53	2.53	21.4	98.3
0.8	0.4	0.5	5.69	2.02	24.25	109.18
0.9	0.4	0.55	5.35	1.82	24.5	121.1
$\mathbf{1}$	0.4	0.6	4.99	1.62	27.98	121.1
1.1	0.45	0.6	4.63	1.44	27.98	134.21
1.2	0.45	0.6	4.43	1.2	31.77	135.21
1.3	0.5	0.6	4.05	1.17	31.77	148.64
1.4	0.53	0.6	3.89	1.07	35.94	148.63
1.5	0.55	0.6	3.83	1.01	40.54	148.63
1.6	0.6	0.65	3.85	1.09	51.16	148.63
1.7	0.65	0.7	3.83	1.02	51.16	134.21
1.8	0.65	0.75	3.87	1.06	57.28	181.94
1.9	0.75	0.8	3.8	1.03	57.28	222.2
2	0.75	0.9	3.46	0.9	64	271.02
2.1	0.75	$\mathbf{1}$	3.36	0.85	64	330
2.2	0.85	1.1	3.16	0.8	64	443
2.3	0.9	1.2	3.05	0.78	64	460

Table 4.1. Summary of the findings for different radii



## **4.3. Effect of variation of the swirl ratio on the vertical**  $V_{\theta}$  **profile**

Identifying the vertical  $V_{\theta}$  profile is essential for engineering purposes because this profile shows the  $V_{\theta,\text{max}}$  and the  $z_{\text{max}}$  (Refan et al., 2017). Therefore, in this section, effect of variation of the S parameter on the vertical V<sub>θ</sub> profile is investigated. The investigation is conducted for  $0.2 \leq S \leq 1.5$ for different tornado radii and results are shown for  $r_0$ =0.8km, 1.0km, 1.5km and 2.0km.

### **4.3.1. Simulation results**

Figure 4.7 shows the vertical  $V_{\theta}$  profile for r<sub>o</sub>=0.8km. The vertical  $V_{\theta}$  profiles are shown at different r locations:  $r=33m$ ,  $r=88m$ ,  $r=r_c=110m$  and  $r=245m$  from the center of the tornado. Figure 4.7shows that the V $\theta$  profile has always a conical shape and the V $\theta_{\text{max}}$  always occurs at elevations less than 30m AGL for all S values. Moreover, Figure 4.7(a) shows that at r=33m from the center the V $\theta_{\text{max}}$  is almost 5.5V<sub>r∞</sub>, and Figure 4.7(b) shows that at r=88m the V $\theta_{\text{max}}$  is almost 5.8V<sub>r∞</sub>. At r=r<sub>c</sub>=the V<sub>θ,max</sub> is almost 6.1V<sub>r∞</sub>. 110m (Figure 4.7(c)). Also, Figure 4.7(d) shows that by moving farther from the r<sub>c</sub>, at r=245m the V $_{\theta,\text{max}}$  decreases to less than 4.0V<sub>r∞</sub>. It implies that the V $_{\theta,\text{max}}$ occurs at the inner core of the tornado. In addition, Figure 4.7 shows that at all distances by increasing the S, the  $z_{\text{max}}$  descends towards the ground and minimizes at S greater than the touchdown S.

Similarly, Figure 4.8 shows the vertical V<sub>θ</sub> profile for r<sub>o</sub>=1.0km at: r=33m, r=88m, r=r<sub>c</sub>=121m and r=245m from the center of the tornado. Figure 4.8 shows that the  $V_{\theta}$  profile has always a conical shape and the  $V_{\theta, max}$  always occurs at elevations less than 30m AGL for all S values. In addition, by increasing the S value, the zmax descends towards the ground. Moreover, Figure 4.8(a) shows that at r=33m from the center the V $_{\theta,\text{max}}$  is almost 1.6V<sub>r∞</sub>, and Figure 4.7(b) shows that at r=88m the V<sub>θ,max</sub> is almost 4.5V<sub>r∞</sub>. At r=r<sub>c</sub>=121m (Figure 4.7(c)) the V<sub>θ,max</sub> is almost 4.9V<sub>r∞</sub>. Figure 4.7(d)



shows that by moving farther from the r<sub>c</sub>, at r=245m the V<sub>θ,max</sub> decreases to less than 4.3V<sub>r∞</sub>. It implies that the  $V_{\theta, max}$  occurs at the inner core of the tornado.

In parallel, Figure 4.9 shows the vertical V<sub> $\theta$ </sub> profile for r<sub>o</sub>=1.5km at: r=33m, r=88m, r=r<sub>c</sub>=148m and r=245m from the center of the tornado. Figure 4.9 shows that for all S values, the vertical  $V_{\theta}$ profile has a conical shape with the  $V_{\theta, max}$  at less than 50m AGL. In addition, by increasing the S value, the z<sub>max</sub> descends towards the ground. Moreover, Figure 4.10(c) shows that the V $_{\theta, max}$  again peaks at r=r<sub>c</sub>=148m and by moving away from the r<sub>c</sub>, the V $_{\theta, max}$  will decrease. Therefore, the V $_{\theta, max}$ occurs at the inner core and the zmax occurs at the radial location corresponding to the rc.

Figure 4.10 shows the vertical V<sub>θ</sub> profile for r<sub>0</sub>=2.0km at different r locations: r=50m, r=150m,  $r=r_c=271$ m and  $r=490$ m from the center of the tornado. Similar to the previous case, in this case it can be seen that the vertical V $\theta$  profile has always a conical shape and the V $\theta$ <sub>max</sub> always occurs at around 60m AGL. Moreover, in this case again by increasing the S value, the zmax descends towards the ground. Furthermore, the V $_{\theta,\text{max}}$  is 3.5V<sub>r∞</sub> and occurs at r=r<sub>c</sub> (Figure 4.10(c)). For this case also the  $V_{\theta, max}$  occurs at the inner core and the  $z_{max}$  occurs at the radial location corresponding to the r<sub>c</sub>.





Figure 4.7. Vertical V $\theta$  profile of different swirl ratios for r<sub>o</sub>=0.8km. a) r=33m; b) r=88m; c)  $r=r_c=110m$ ; d)  $r=245m$ 



Figure 4.8. Vertical V<sub> $\theta$ </sub> profile of different swirl ratios for r<sub>o</sub>=1.0km. a) r=33; b) r=88; c)  $r=r_c=121m$ ; d)  $r=245m$ 





Figure 4.9. Vertical V $\theta$  profile of different swirl ratios for r<sub>o</sub>=1.5km. a) r=33; b) r=88m; c)  $r=r_c=148m$ ; d)  $r=245m$ 



Figure 4.10. Vertical V<sub> $\theta$ </sub> profile of different swirl ratios for r<sub>o</sub>=2.0km. a) r=50; b) r=150m; c) r=rc=271m; d) r=490m



#### **4.3.2. Summary of findings**

Investigation of the vertical V<sub>θ</sub> profiles shows that for all radii, the vertical V<sub>θ</sub> profile has a conical shape, where the location of the  $V_{\theta, max}$  is close to the ground and descends towards the surface by increasing the S parameter. These close-to-ground maxima is always in the range of 21m to 64m of the ground and differentiates tornadic flows from the SL flows. In addition, the  $V_{\theta, max}$  and the zmax always occur within the inner core of the tornado.

#### **4.3.3. Comparison of the results to the laboratory and radar measurements**

Tari et al. (2010) showed that by increasing the S parameter, the zmax descends towards the ground. They also reported the vertical  $V_{\theta}$  profile has a conical shape and the nose-like peak occurs at the swirl ratio of the  $V_{\theta, max}$ . However, their laboratory simulator was not capable of reporting at less than 20m AGL. Refan (2014) also showed that the vertical  $V_{\theta}$  profile has a conical shape, but reported the zmax in the range of 30 to almost 200m AGL. In addition, Doppler radar measurements of Wurman et al. (1997) showed that the Vθ,max occurs close to the ground at around 30m AGL. However, they were not able to evaluate for less than 30m AGL.

#### **4.4. Effect of variation of the swirl ratio on the radial**  $V_{\theta}$  **profile**

The radial V<sub>θ</sub> profile will provide information of the V $_{\theta,\text{max}}$ , and changing the S parameter changes the V<sub>θ</sub> profile (Refan, 2014). In addition, the radial V<sub>θ</sub> profile can provide the V<sub>θ,max</sub> at any elevation. Thus, in this section effect of variation of the S parameter on the radial  $V_{\theta}$  profile is investigated. The investigation is conducted for  $0.2 \le S \le 1.5$  on  $0.7 \text{km} \le r \le 2.3 \text{km}$ . For the sake of brevity, the radial V<sub>θ</sub> profiles of r<sub>o</sub>=0.8km, r<sub>o</sub>=1.0km, r<sub>o</sub>=1.7km, r<sub>o</sub>=1.8km and r<sub>o</sub>=2.0km are shown only. Figures 4.11 to 4.15 show the radial V $\theta$  profiles for the these r<sub>o</sub> radii at elevations z=51m, 18.5m, 9.5m, and 4.5m.



#### **4.4.1. Simulation results**

#### **4.4.1.1.** Pattern of the radial  $V_\theta$  profile

Figure 4.11 shows the V<sub>θ</sub> profile for r<sub>o</sub>=0.8km at different heights. Based on Figure 4.1 swirl ratios of touchdown and the V $_{\theta,\text{max}}$  for r<sub>o</sub>=0.8km are S=0.4 and 0.5, respectively. Figures 4.11(a) and 4.11(b) show that at  $z=51$ m and  $z=18.5$ m the radial V $\theta$  profiles resemble the RCVM profile at different S values. Figures 4.11(c) and 4.11(b) show the radial V $\theta$  profiles at z=9.5m and z=4.5m, respectively. As can be seen in these figures, at these elevations the  $V_\theta$  profile for S values beyond the touchdown S no longer resemble the RCVM flow, rather two peaks occur on the profile. However, for S values smaller than the touchdown S, the profiles still resemble the RCVM. Therefore, tit can be concluded for  $r_0 = 0.8$ km two peak occurs at  $z < 10$ m AGL for S values beyond the touchdown S.

Figure 4.12 shows the V<sub>θ</sub> profile for r<sub>o</sub>=1.0km at different heights. Based on Figure 4.1 swirl ratios of touchdown and the  $V_{\theta,\text{max}}$  for r<sub>o</sub>=1.0km are S=0.4 and 0.6, respectively. Figures 4.12(a) and 4.12(b) show that at  $z=51$ m and  $z=18.5$ m the profiles have a trend similar to RCVM flow for different S values. Figures 4.12(c) and 4.12(d) show the radial V $\theta$  profiles at z=9.5m and z=4.5m, respectively. It can be seen that at these elevations the  $V_{\theta}$  profiles no longer resemble the RCVM flow, rather two peaks occur on the profiles for S values beyond the touchdown S. However, for S values smaller than the touchdown the profiles resemble the RCVM profile. Therefore, it can be concluded that for  $r_0 = 1.0$ km at S of touchdown and beyond that, two peaks occur at  $z < 10$ m AGL. Figure 4.13 shows the V $\theta$  profile for r<sub>o</sub>=1.7km at different heights. Based on Figure 4.1 swirl ratios of touchdown and the  $V_{\theta,\text{max}}$  for r<sub>0</sub>=1.7km are S=0.65 and S=0.7, respectively. Figure 4.13(a) shows that at  $z=51m$ , the radial V $\theta$  profiles resemble the RCVM flow for all S values. Figure 4.13(b) shows the radial V $\theta$  profiles at z=18.5m. At this elevation, the profile has two peaks for S



greater than the touchdown S, and no longer resembles the RCVM profile. Similarly, Figures 4.13(c) and 4.13(d) respectively show the profiles at z=9.5m and 4.5m. It can be seen that at these elevations the profiles have two peaks for S beyond the touchdown S  $(S=0.65)$ . Therefore, simulation results for r<sub>o</sub>=1.7km show that at z<20m the V $_{\theta}$  profile has two peaks, whereas for z>20 the profile resembles the RCVM flow.

Figure 4.14 shows the V $\theta$  profile for r<sub>0</sub>=1.8km at different heights and various S values. Based on Figure 4.1 swirl ratios of touchdown and the  $V_{\theta,\text{max}}$  for r<sub>o</sub>=1.8km occurs at S=0.65 and S=0.75, respectively. Figure 4.14 shows that at different elevations of  $z=51m$ ,  $z=18.5m$ ,  $z=9.5m$  and  $z=4.5$ m the radial V $\theta$  profiles have two peaks for S values beyond the touchdown S. Therefore, for  $r_0$ =1.8km two peaks always occur at all elevations for the S values beyond touchdown.

Similarly, Figure 4.15 shows the V $\theta$  profile for r<sub>o</sub>=2.0km at different heights and various S values. Based on Figure 4.1 swirl ratios of touchdown and the  $V_{\theta,\text{max}}$  for r<sub>o</sub>=2.0km are 0.75 and 0.9, respectively. Figure 4.15 shows that at different elevations of  $z=51m$ ,  $z=18.5m$ ,  $z=9.5m$  and  $z=4.5$ m the radial V $\theta$  profiles have two peaks for S values beyond the touchdown S. Therefore, for  $r<sub>o</sub>=2.0km$  two peaks always occur at all elevations for the S values beyond touchdown.





Figure 4.11. Radial V $_\theta$  profile of different swirl ratios for r<sub>o</sub>=0.8km. a) z=51m; b) z=18.5m; c)  $z=9.5m$ ; d)  $z=4.5m$ 



Figure 4.12. Radial V $\theta$  profile of different swirl ratios for r<sub>o</sub>=1.0km. a) z=51m; b) z=18.5m; c)  $z=9.5m$ ; d)  $z=4.5m$ 





Figure 4.13. Radial V $\theta$  profile of different swirl ratios for r<sub>o</sub>=1.7km. a) z=51m; b) z=18.5m; c) z=9.5m; d) z=4.5m



Figure 4.14. Radial V<sup>θ</sup> profile of different swirl ratios for ro=1.8km. a) z=51m; b) z=18.5m; c) z=9.5m; d) z=4.5m





Figure 4.15. Radial V $\theta$  profile of different swirl ratios for r<sub>o</sub>=2.0km. a) z=51m; b) z=18.5m; c)  $z=9.5m$ ; d)  $z=4.5m$ 

## **4.4.1.2. Location of occurrence of peaks on the profile**

Figure 4.16 represents the occurrence of two peaks on the V $\theta$  profile of the tornados with r<sub>o</sub>=0.8km,  $r_0$ =1.0km,  $r_0$ =1.5km,  $r_0$ =2.0km at  $z$ =4.5m. Profiles are shown at the S parameter that produces the  $V_{\theta, max}$ . Figure 4.16(a) shows that for r<sub>o</sub>=0.8km, the first peak occurs at almost 35m from the tornado center and  $r_c$  is 110m (Figure 4.6). Similarly, Figure 4.16(b) shows that  $r_o=1.0$ km the first peak occurs at almost 40m away from the center while the  $r_c$  is  $121m$  (Figure 4.6). Also, Figure 4.16(c) shows that for  $r_0 = 1.5$ km the first peak is almost 50m from the tornado center where  $r_c$  is 148m. Finally, Figure 4.16(d) shows that for  $r_0 = 2.0$ km the first peak occurs almost 200m away from the center whereas the r<sub>c</sub> is 271m. Therefore, it can be concluded that for different r<sub>0</sub> tornados, the first peak occurs within the inner core.





Figure 4.16. Tangential velocity profiles at z=4.5m and the S corresponding to double-peak. a)  $r_0$ =0.8km; b)  $r_0$ =1.0km; c)  $r_0$ =1.5km; d)  $r_0$ =2.0km. It can be seen that for larger radii, higher S is required to observe the double-peak.

## **4.4.2. Summary of findings**

Figures 4.11 through 4.15 show that for ro $\leq$ 1.6km, the radial V $_{\theta}$  profiles resemble the RCVM profile at  $z>10$ m AGL before and after the touchdown; whereas for  $z\leq10$ m they have a different profile with two peaks on it after the touchdown. Similarly, for ro $\geq$ 1.8 the radial V $\theta$  profiles always have two peaks after the touchdown at all elevations. Occurrence of two peaks on the profile can be related to the strong shear force close to the ground, which causes increased intensity of the wider tornados despite their smaller  $V_{\theta,\text{max}}/V_{\text{r}\infty}$  than smaller tornados.



#### **4.4.3. Comparison of the results to the laboratory and CFD models**

Figure 4.12 shows that for  $r_0=1.0$ km, the velocity profiles at  $z=51$ m and 18.5m resemble the RCVM profile. This finding is in agreement with the findings of Lewellen et al. (1997) which reported that the V<sub>θ</sub> profile for r<sub>o</sub>=1.0km follows the RCVM trend. Likewise, Refan (2014) reported occurrence of two peaks on the radial  $V_{\theta}$  profile for S>1.0, but did not discuss the elevation and the ro for which this two peak occurs. Moreover, Refan (2014) did not discuss any reason for this observation. Church et al. (1979) used a laboratory tornado simulator and showed that the tornado velocity profile has two peaks close to the ground; however, this profile was not the  $V_{\theta}$  profile, rather it was the magnitude of the velocity profile. They attributed this observation to the strong shear force close to the ground.

## **4.5. Effect of the swirl ratio on the vertical structure of the tornados**

Tari et al. (2010) and Refan (2014) showed that changing the S parameter will change the structure of the tornados from a single-cell to a double-cell structure. Hangan and Kim (2008), Refan (2014), Refan et al. (2017) stated that before the touchdown, the tornado has a jet-like structure, during the touchdown a vortex breakdown occurs aloft, and in transition to the double-cell, the  $V_{\theta, max}$ occurs. Figure 2.3 shows the vertical structure of tornados as proposed by Lewellen (1976). In the present section, the simulation results for the vertical structures of the tornados are investigated. For this purpose, the vertical structures are shown for  $r_0=0.8k$ ,  $r_0=1.0km$ ,  $r_0=1.5km$  and  $r_0=1.8km$ . The S that produces the  $V_{\theta, max}$  for each of these r<sub>o</sub> are taken from Figure 4.10. It can be implied form Figure 4.10 that at  $S=0.3$ , there is no touchdown for any r<sub>o</sub>.

### **4.5.1. Simulations results**

Figure 4.17 shows the tornado wind-field for  $r_0$ =0.8km at S=0.3, S=0.5, and S=0.8. The S=0.5 is taken from Figure 4.10. Figure 4.17(a) shows the wind-field at  $S=0.3$ . It can be seen in this figure



that the flow is jet-like with no downdraft. This structure is similar to the structure shown by Lewellen (1976) for a single-cell structure. Figure 4.17(b) shows that by increasing the S to  $S=0.5$ , which is the touchdown S, the vortex breakdown occurs aloft. Afterwards at  $S=0.6$ , which is the S producing the  $V_{\theta, max}$ , the tornado transitions from single-cell structure to double-cell structure (Figure 4.17(c)). The vortex breakdown aloft at the touchdown and the transition at the S producing the  $V_{\theta, max}$  agree well with the proposed structures by Lewellen (1976) as shown in Figures 2.3(b) and 2.3(c), respectively.

Figure 4.18 shows the tornado wind-field for  $r_0 = 1.5$ km at S $= 0.3$ , S $= 0.5$ , and S $= 0.6$ . The S parameters of 0.5 and 0.6 are taken from Figure 4.10, which are, respectively, the touchdown S and the S producing the V $_{\theta,\text{max}}$ . Figure 4.19(a) shows the wind-field at S=0.3. It can be seen in this figure that with S=0.3 the flow is jet-like with no downdraft, which is similar to the single-cell structure proposed by Lewellen (1976), as shown in Figure 2.3(a). Figure 4.19(b) shows that by increase of the S to  $S=0.5$ , which is the touchdown S, the vortex breakdown occurs aloft, and afterwards at  $S=0.6$ , which is the S producing the  $V_{\theta,\text{max}}$ , the tornado transitions from single-cell structure to double-cell structure (Figure 4.19(c)). The vortex breakdown aloft at the touchdown and the transition at the S producing the  $V_{\theta,\text{max}}$  agree well with Figures 2.3(b) and 2.3(c), respectively.

Figure 4.19 shows the tornado wind-field for  $r_0 = 2.0$ km at  $S = 0.3$ ,  $S = 0.65$ , and  $S = 0.75$ . The two latter values are, respectively, the touchdown S and the S producing the  $V_{\theta, max}$  taken from Figure 4.10. Again, it can be seen in Figure 4.20(a) that at  $S=0.3$ , the flow is jet-like with no downdraft, which is similar to the single-cell structure proposed by Lewellen (1976), as shown in Figure 2.3(a). Figure 4.20(b) shows that by increase of the S to S=0.5, which is the touchdown S, the vortex breakdown occurs aloft, and afterwards at  $S=0.6$ , which is the S producing the  $V_{\theta, max}$ , the



tornado transitions from single-cell structure to double-cell structure (Figure 4.20(c)). The vortex breakdown aloft at the touchdown and the transition at the S producing the  $V_{\theta,\text{max}}$  agree well with Figures 2.3(b) and 2.3(c), respectively.

The reason that the double-cell structure occurs is the large outward centrifugal force which is produced due to increase of the S parameter (Davis-Jones, 1973; Haan et al., 2008). Hence, it can be implied that for transitioning from a single-cell to a double-cell tornado, more energy is required. In other words, since the S parameter is the ratio of the angular momentum to the radial momentum, therefore the wider tornados require more momentum and energy to have transition from single-cell to double-cell tornados after the touchdown.

### **4.5.2. Summary of findings**

Simulations show that by increase of the S, flow changes from a single-celled to a vortex breakdown aloft at the touchdown stage, and finally to a double-celled structure at the S producing the V<sub>θmax</sub>.

## **4.5.3. Comparison of the results to the CFD and laboratory models**

Hangan and Kim (2008) reported that for  $r_0 = 1.0$ km, variation of the S parameter from 0.28 to 0.8 covers the main stages of the tornado genesis from the formation of a laminar core vortex, the aloft vortex break down to the touchdown of the turbulent vortex. Also, Refan et al. (2017) reported 0.8<S<1.4 as the range of producing the double-celled tornados for the tornado radii of 0.2km to 2.0km. Dominguez and Selvam (2017) stated that for  $r_0 = 1.0$ km at S=0.3, the flow is jet-like and no touchdown occurs, whereas the touchdown S and S of  $V_{\theta,\text{max}}$  are, respectively, 0.4 and 0.6. Refan (2014) stated that for S=0.96, the structure of tornados is double-celled. Therefore, the simulations of the vertical structure of the tornados in the present study agree well with the previous studies.





Figure 4.17. Tornado wind field for  $r_0 = 0.8$ km. a) S=0.3, jet-like and single-cell structure; b) S=0.4, vortex breakdown aloft at touchdown; c) S=0.5, beyond touchdown, double-cell structure; d) zoomed view of single-cell structure; e) zoomed view of vortex breakdown aloft; f) zoomed view of double cell structure



Figure 4.18. tornado wind field for ro=1.5 km. a) S=0.3, jet-like and single-cell structure; b) S=0.50: touchdown, vortex breakdown aloft; c) S=0.6: double-cell structure; d) zoomed view of single-cell structure; e) zoomed view of vortex breakdown aloft; f) zoomed view of double cell



structure



Figure 4.19. Tornado wind field for  $r_0 = 2.0$ km. a) S=0.3, jet-like and single-cell structure; b) S=0.75, vortex breakdown aloft at touchdown; c) S=0.9, beyond touchdown, double-cell structure; d) zoomed view of single-cell structure; e) zoomed view of vortex breakdown aloft; f) zoomed view of double cell structure

## **4.5.4. Comparison of the simulation results to the laboratory and radar measurements**

Hangan and Kim (2008) used a laboratory model and stated that the 1998 Spencer tornado with ro=0.8km is a double-celled tornado. In addition, Lee and Samaras (2004) used Doppler radar and reported a double-cell structure for the 2003 Manchester tornado with  $r_0$ =0.8km. Similarly, Wakimoto et al (2016) used Doppler radar and showed that the 2013 El Reno tornado with  $r<sub>o</sub>=2.3km$ , are double-celled tornados. Results of the present study in Figures 4.10 and 4.13 show that after the touchdown, the r<sub>c</sub>=110m for r<sub>0</sub>=0.8km and for r<sub>0</sub>=2.3km, the r<sub>c</sub> is 460m, and are therefore double-celled. It can be implied that the simulation produces acceptable results compared to the radar measurements.



## **4.6. Verification of the simulation results against the radar measurements**

In this section, the simulation results will be verified against the radar measurements of the actual data. As discussed in Chapter 3, the verification criteria are: the vertical tornado structure, r<sup>c</sup> and  $z_{\text{max}}$ . The radar measurements of 6 actual tornados on their structure,  $r_c$  and  $z_{\text{max}}$  are available, as shown in Table 4.3.

Comparison of the structure of the tornados in Table 4.3 shows that for all 6 cases, the structures match at both simulations and radar measurements. Also, comparison of the  $r_c$  from the radar and simulation results in Table 4.3 shows that the simulation and radar reasonably agree in cases of Spencer and Manchester tornados. However, for cases of El Reno and Bridge, Creek, Moore tornados, the simulations report smaller  $r_c$  than the radar measurements. This discrepancy is due to the debris effect in the radar measurements (Kosiba and Wurman, 2010) which causes the radars measure higher values for the rc.

Also, Table 4.3 shows  $z_{\text{max}}$  of the actual tornados by radar and simulations. The  $z_{\text{max}}$  by radar is reported for Spencer, Manchester, and Goshen Wyoming tornados, and the simulation results for zmax of these three tornados agree closely with the radar measurements. However, for the 1999 Dimmit TX, the 2013 El Reno and the 1999 Bridge Creek Moore tornados the z<sub>max</sub> from the Doppler radar are not available. Refan et al. (2017) stated that if two sailing criteria meet in comparison of the simulations to the radar measurements, then the simulations are reliable. Therefore, since the structure and the  $r_c$  of the simulations for these three tornados comply with the radar data, it can be claimed that the simulations in the present study are valid.

Likewise, Figures 4.20 through 4.22 compares the radial  $V_{\theta}$  profile of the actual tornados to the simulation results. Figures 4.20 through 4.22, respectively, represent the 1995 Dimmit, Texas, 1998 Spencer, and 2003 Manchester tornados. Comparisons show that the simulation results



resemble the RCVM profile, as do the radar measurements. In addition, the  $r_c$  from both simulations and radar measurements fairly agree with each other.

Verification of the simulation results for the vertical structure,  $r_c$ ,  $z_{\text{max}}$  and the radial V $\theta$  profiles of tornados shows close agreement of simulations with the radar measurements.

Tornado	$r_{o}$ (km)	Technique	Structure	$r_c(m)$	$Z_{max}(m)$
Spencer (1998)	0.8	Doppler radar (Wurman et al., 1998)	Double-celled	120	20
		Simulation results	Double-celled	109	21.4
Manchester (2003)	0.8	Doppler radar (Sarkar and Gallus, 2010)	Double-celled	130	20
		Simulation results	Double-celled	109	21.4
Goshen, Wyoming	1.0	Doppler radar (Wurman et al.2013)	Double-celled	140	30
(2009)		Simulation results	Double-celled	121	27.5
Dimmit, Texas	1.0	Doppler radar (Wurman and Gill, 2000)	Double-celled	150	NA
(1999)		Simulation results	Double-celled	121	27.5
El Reno (2013)	2.3	Doppler radar (Bluestein et al, 2015; Wakimoto et al. 2016)	Double-celled	650	NA
		Simulation results	Double-celled	500	65
<b>Bridge Creek</b>	0.8	Doppler radar (Burgess et al., 2002)	Double-celled	175	<b>NA</b>
Moore(1999)		Simulation results	Double-celled	110	21.4

Table 4.2. Comparison of the vertical structure, r<sub>c</sub> and z<sub>max</sub> of radar measurements to simulations



## **4.7. Summary of the chapter**

In this chapter, the S values corresponding to the touchdown and the  $V_{\theta, max}$  were initially investigated. Afterwards, the absolute  $V_{\theta, max}$  and the  $V_{\theta, max}$  at  $z=3.3$  were investigated. In addition, the zmax and the rc for different ro radii were reported. Subsequently, the effect of variation of the S parameter on the radial and vertical  $V_{\theta}$  profiles and the structure of the tornados were investigated. It was found that the  $V_{\theta, max}$  always occurs at  $21$ m $\lt$ z $\lt$ 64m. In addition, it was observed that for r<sub>o</sub>≤1.8km the radial V<sub>θ</sub> profiles at z>10m are similar to the RCVM flow, and at z<10m the profile has two peaks. In addition, for r<sub>o</sub> $\geq$ 1.8km, the radial V $\theta$  profiles always have two peaks. Occurrence of double peaks on the  $V_{\theta}$  profiles is due to strong shear forces and is the main cause of the building damages.



### **CHAPTER 5. SUMMARY AND CONCLUSIONS**

In this chapter, a summary of the study is initially reviewed and the finding and conclusions are presented.

### **5.1. Summary of the study**

In the literature review it was revealed that the  $V_{\theta}$  component is the main velocity component of tornadic flows that exerts forces to buildings. Therefore, it is necessary to evaluate the  $V_{\theta}$  profile of tornados in order to design tornado-resistant buildings. However, it was revealed that the infield measurements, such as the Doppler Radar, suffer from limitations of their beams, and cannot evaluate the  $V_{\theta}$  profiles for less than 20m AGL. In parallel, the post-damage investigations are capable of relating the tornado damages to its maximum velocity, but cannot evaluate the  $V_{\theta}$ profile. The satellite based measurements also suffer from the same shortcomings and thus are not capable of evaluating the  $V_{\theta}$  profile close to the ground. Because of the shortcomings of the infield measurements and post-damage investigations, the experimental TVCs were built in order to model to the tornados in laboratory. The laboratory TVCs advanced the tornado-related studies by showing that in modeling the tornados there are two parameters that must be investigated in order to evaluate the  $V_{\theta}$  profile: S and  $r_{o}$  parameters. However, laboratory TVCs suffer from scaling limits and cannot evaluate the  $V_{\theta}$  profile at less than 10m AGL. The CFD models can computationally simulate the TVCs and evaluated the  $V_\theta$  profile close to the ground, but the results of the CFD models is limited to  $r_0 = 1.0$ km, while the actual tornados have the radii of up to 2.3km. Hence, there is a need to propose a model that can evaluate the  $V_{\theta}$  profile of different r<sub>o</sub> radii at less than 10m AGL.



## **5.2. Conclusions**

In investigating the V $_{\theta,\text{max}}$  of tornados for different r<sub>o</sub> radii, and also the V $_{\theta,\text{max}}$  at z=3.3m, the following conclusions are made:

## **1. Max. V vertical location zmax is always in the range of 21m to 64m AGL**

It was observed that for different radii, always  $21$ m $\leq$ z<sub>max</sub> $\leq$ 64m, whereas the radar measurements show that  $30 \text{m} \leq \text{zmax} \leq 200 \text{m}$ .

Also, the vertical  $V_{\theta}$  profile of tornados resembles a conical shape where the maximum occurs on the nose-like peak of the cone, as shown in Figure 5.1. This conical shape distinguishes tornadic flows from SL flows.



Figure 5.1. Vertical V $_{\theta}$  profile of tornados. a) 13m away of the tornado center for r<sub>o</sub>=0.8km; b) 13m away of the tornado center for  $r_0 = 1.0 \text{km}$ ; c) 88m away of the tornado center for  $r_0 = 1.5 \text{km}$ ; d) 150m away of the tornado center for  $r_0 = 2.0$ km



#### **2. Increasing the r<sup>o</sup> increases the zmax**

By increasing the  $r_0$  from  $r_0$ =0.7km to 1.9km, the  $z_{\text{max}}$  will also increase from 21m to 57m. However, for  $r_0$ >2.0km, the  $z_{\text{max}}$  is constant at 64m.

# **3. For ro≤1.6km the radial V<sup>θ</sup> profiles above 10m of the ground resemble the RCVM profile for different S values, whereas at less than 10m of the ground the profile has two peaks for S greater than the touchdown S**

Simulations show that for r<sub>o</sub>≤1.6km, regardless of increasing the S value, the V $\theta$  profiles at z>10 always resemble the RCVM profile, whereas at  $z$ <10m AGL, the radial  $V_{\theta}$  profile has two peaks for the S value greater than the touchdown S. Figures  $5.2(a)$ ,  $5.2(b)$ ,  $5.3(a)$  and  $5.3(b)$  shows this observation.

## **4.** For  $r_0 \geq 1.8$ km the radial  $V_0$  profiles below and above  $z=10$ m have two peaks for the S **greater than the touchdown S**

For r<sub>o</sub> $\geq$ 1.8km the radial V<sub>θ</sub> profiles resemble the RCVM for S smaller than the touchdown S; whereas for S greater than the touchdown S, the profiles no longer resemble the RCVM flow, rather two peaks occur on the profile. Figures 5.2 and 5.3, respectively, show the radial  $V_{\theta}$  profiles at z=9.5m and z=5.1m for different ro. It can be seen that for  $r_0=2.0$ km, the radial V $\theta$  profiles always have two peaks, whereas for  $r_0 = 0.8$ km and 1.5km the profiles the two peaks occur only at  $z$ <10m AGL. Figures 5.2(c), 5.2(d), 5.3(c) and 5.3(d) shows this observation.





Figure 5.2. Radial V $\theta$  profile at z=9.5m AGL. a) r<sub>o</sub>=0.8km; b) r<sub>o</sub>=1.5km; c) r<sub>o</sub>=1.7km; d) ro=2.0km



Figure 5.3. Radial V<sup>θ</sup> profile at z=51m AGL. a) ro=0.8km; b) ro=1.5km; c) ro=1.7km; d) ro=2.0km



## **5. Increasing the r<sub>0</sub> reduces the V<sub>θ,max</sub>/V<sub>r</sub>** $_{\infty}$

Investigating the  $V_{\theta, max}$  at different elevations above and below 10m shows that an increase of r<sub>o</sub> causes the  $V_{\theta, max}/V_{r\infty}$  to decrease.

### **5.3. Suggestions for future work**

This study, despite being the first to measure the absolute  $V_{\theta,\text{max}}$ ,  $Z_{\text{max}}$ ,  $r_c$  and  $V_{\theta,\text{max}}$  at z=3.3m of different tornado radii, has some limits. Based on the limitation of the present study, the future paths of work are suggested as follows:

#### **1. Investigation of the Vθ,max for different tornado radii with constant AR.**

In the present study swirl ratio was considered as  $S=V_{\theta}/(2(AR)V_{r\infty})$ . Reorganizing this yields  $V_{\theta} = 2(AR)(V_{r\infty})(S)$ . Since  $AR = H_0/r_0$ , it can be implied that  $H_0$  is directly proportional to the  $V_{\theta}$ , and thus it is a significant factor in determining the tornado intensity. However, in the present study, H<sup>o</sup> was constant and equal to 1000m, and 0.7km≤ro≤2.3km. Hence, the study was conducted for varying AR. Future studies can use variable  $H_0$  in order to have constant AR.

## **2. Using refined grids to investigate the triple-celled structures**

In the present study, the double-cell tornados were observed in the simulations. However, although it is expected that by increase of the S parameter a triple-cell tornado occurs, there is not such observation in the present study, which is due to insufficient MGS away from the ground. In fact, the triple-cell tornados require extremely small scale modeling in the computation, whereas the present study used MGS=0.001H<sup>o</sup> with a growing factor of 1.1. Further refinement at this moment is impossible due to the storage limits in the computer modeling. Future studies can use higher grid resolutions to capture these small scale features.



## **3. Using a different computational domain**

In the present study, the computational domain of Lewellen et al. (1997) was used and the boundary conditions were taken from Wilson and Rotunno (1986). However, other computational domains with different boundary conditions can simulated and compared to the present study. In this regard, the computational model of Ishihara et al. (2012) is an alternative computational domain which can be used for this purpose. Figures 2.15 and 2.16, respectively, show the schematics of the computational domains of the present study and Ishihara et al. (2012). The difference between these two computational domains has not been studied before.



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